

DANSE

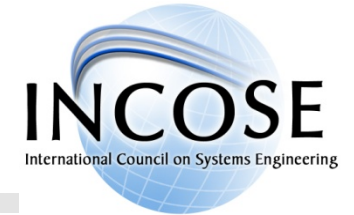
Designing for **A**daptability and evolution**N** in
System of systems **E**ngineering

An Effective, Tool-Supported Methodology for
SoS Engineering in Europe

Near-final results from the three-year DANSE project.



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DANSE

Designing for **A**daptability and evolution**N** in System of systems **E**ngineering

Systems of Systems Concepts

What does DANSE mean by a system of systems?
To what kinds of projects does this methodology
apply?

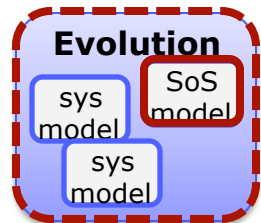
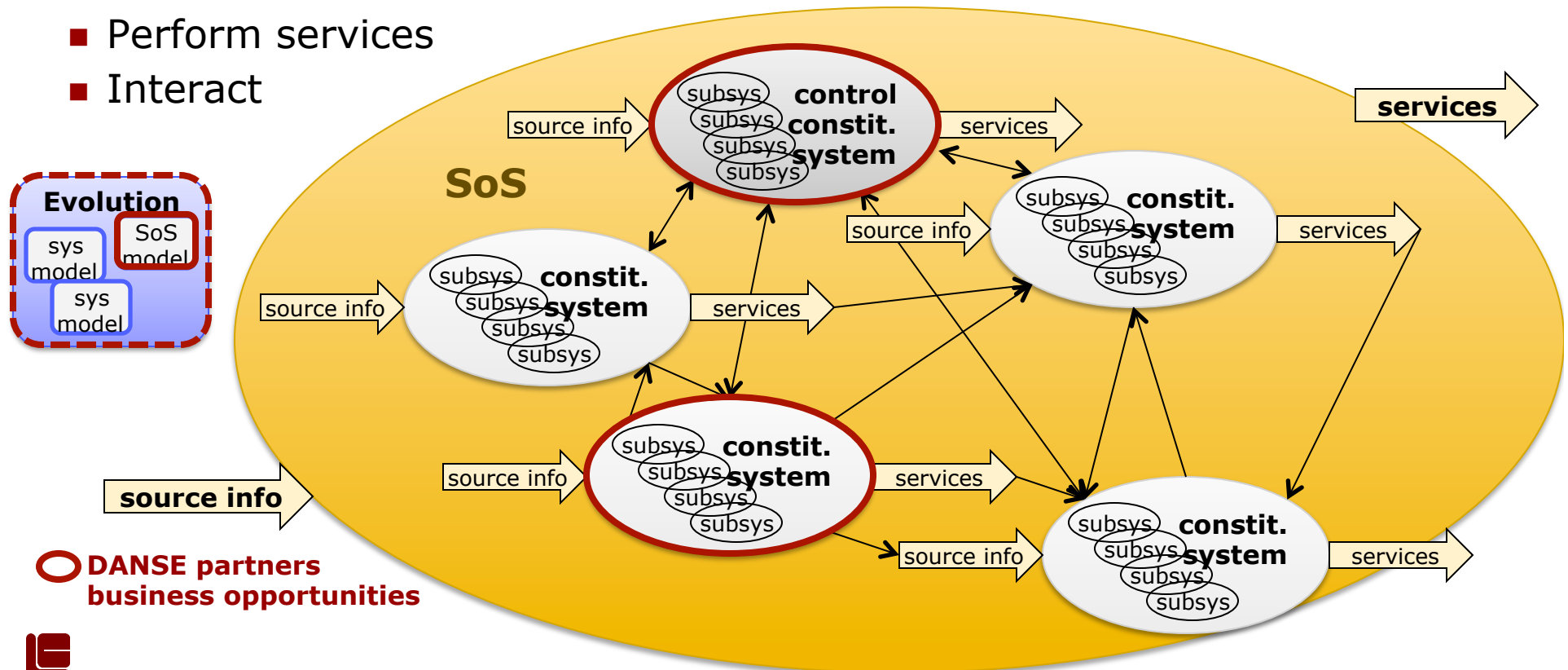
Architecture of an SoS

Constituent systems

- Independently operated and managed
- Gather/receive source info
- Perform services
- Interact

System of systems

- Provides emergent services through system interactions
- Can be modeled
- May need control



DANSE partners
business opportunities

SoS Characteristics

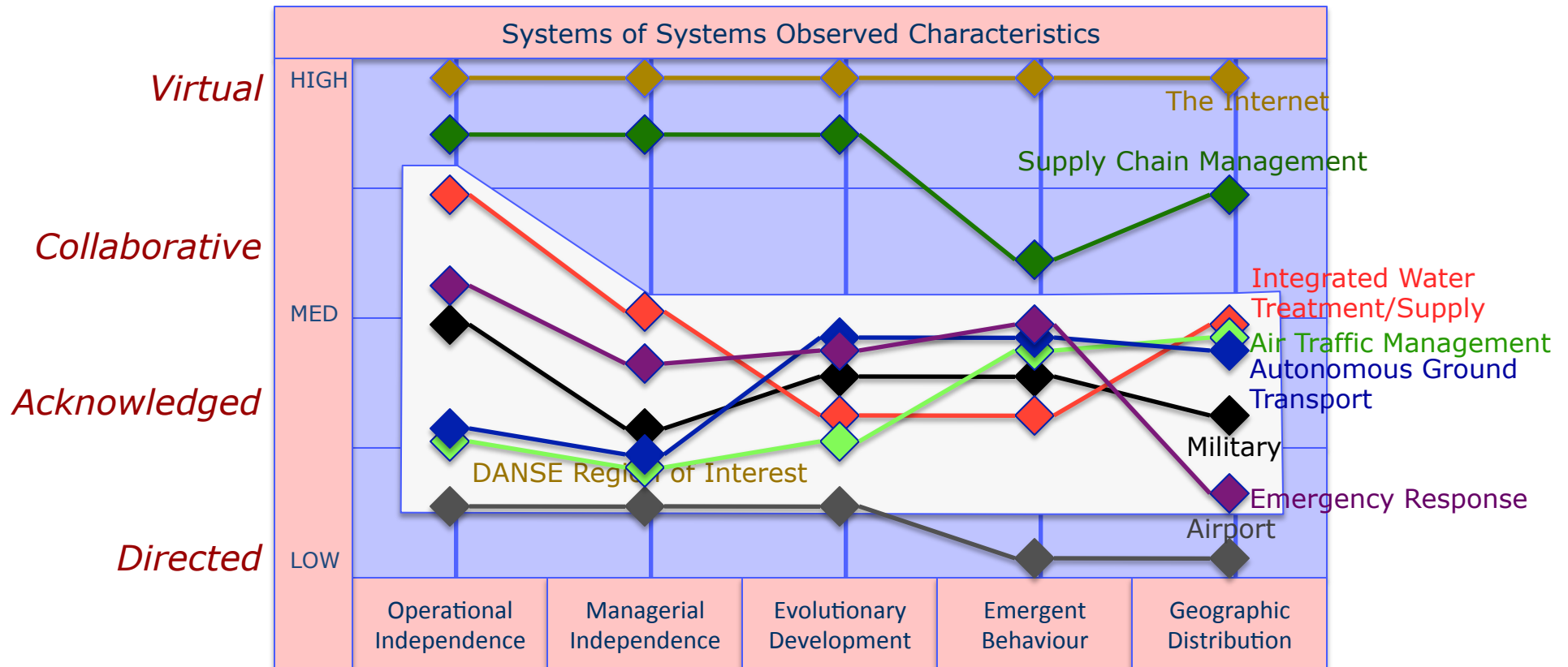
A System is a "System of Systems" if it exhibits significant amounts of:

- **Emergent behavior** - SoS performs functions not achievable by the independent component systems
- **Geographic distribution** - geographic extent forces the elements to exchange information in a remote way
- **Evolutionary development** - functions and purposes are added, removed and modified in an ongoing way
- **Operational independence** - component systems have purpose even if detached
- **Managerial independence** - component systems are developed and managed for their own purposes

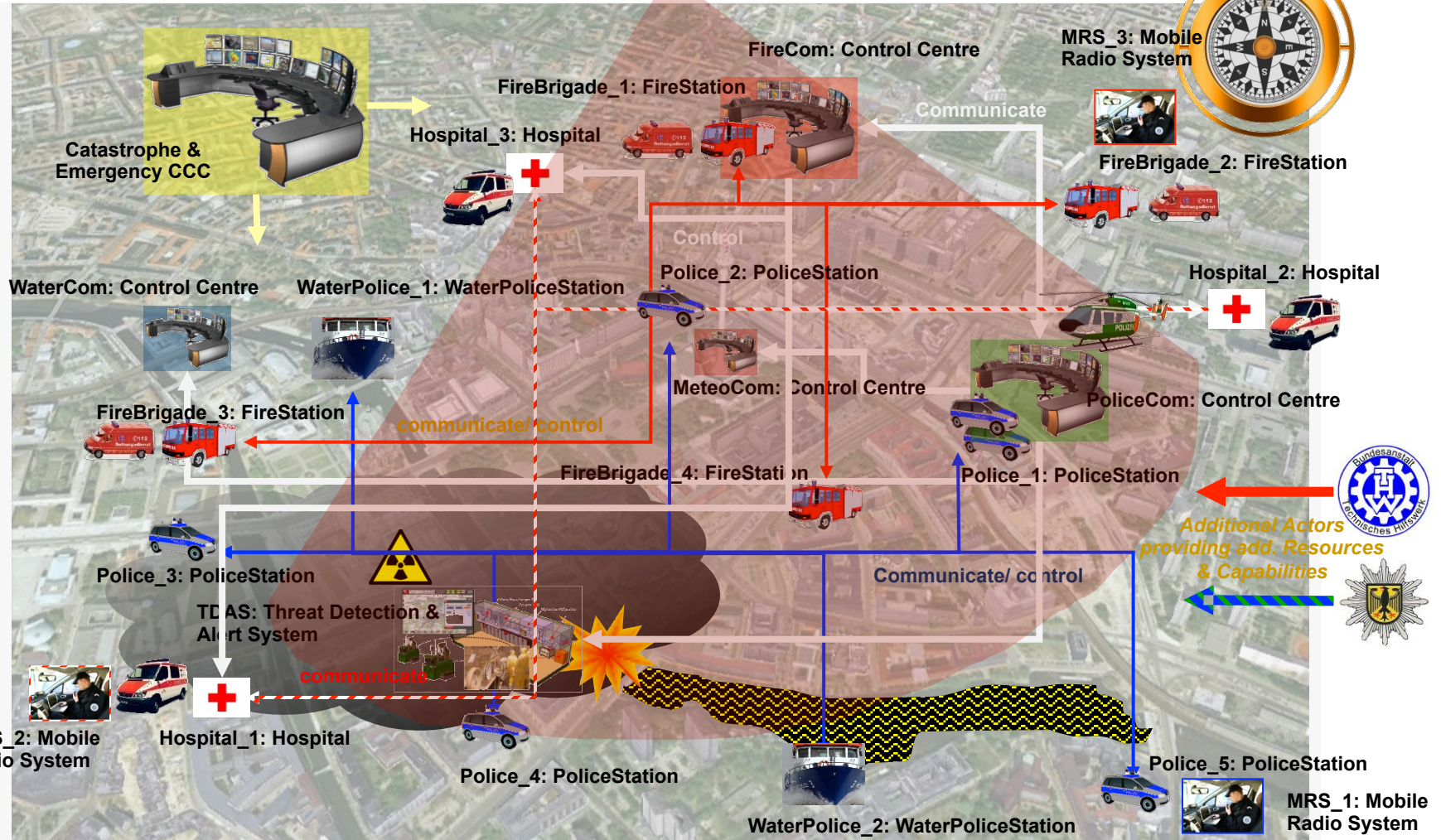
- Mark Maier 1998, "Architecting Principles for SoS," *Systems Engineering* (INCOSE)

Differing Levels of "SoS-ness"

Primary work: Honourcode



Emergency Response SoS

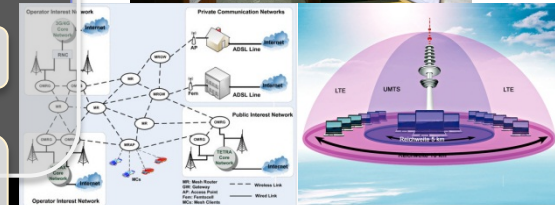
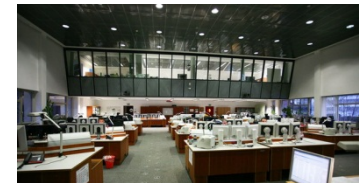
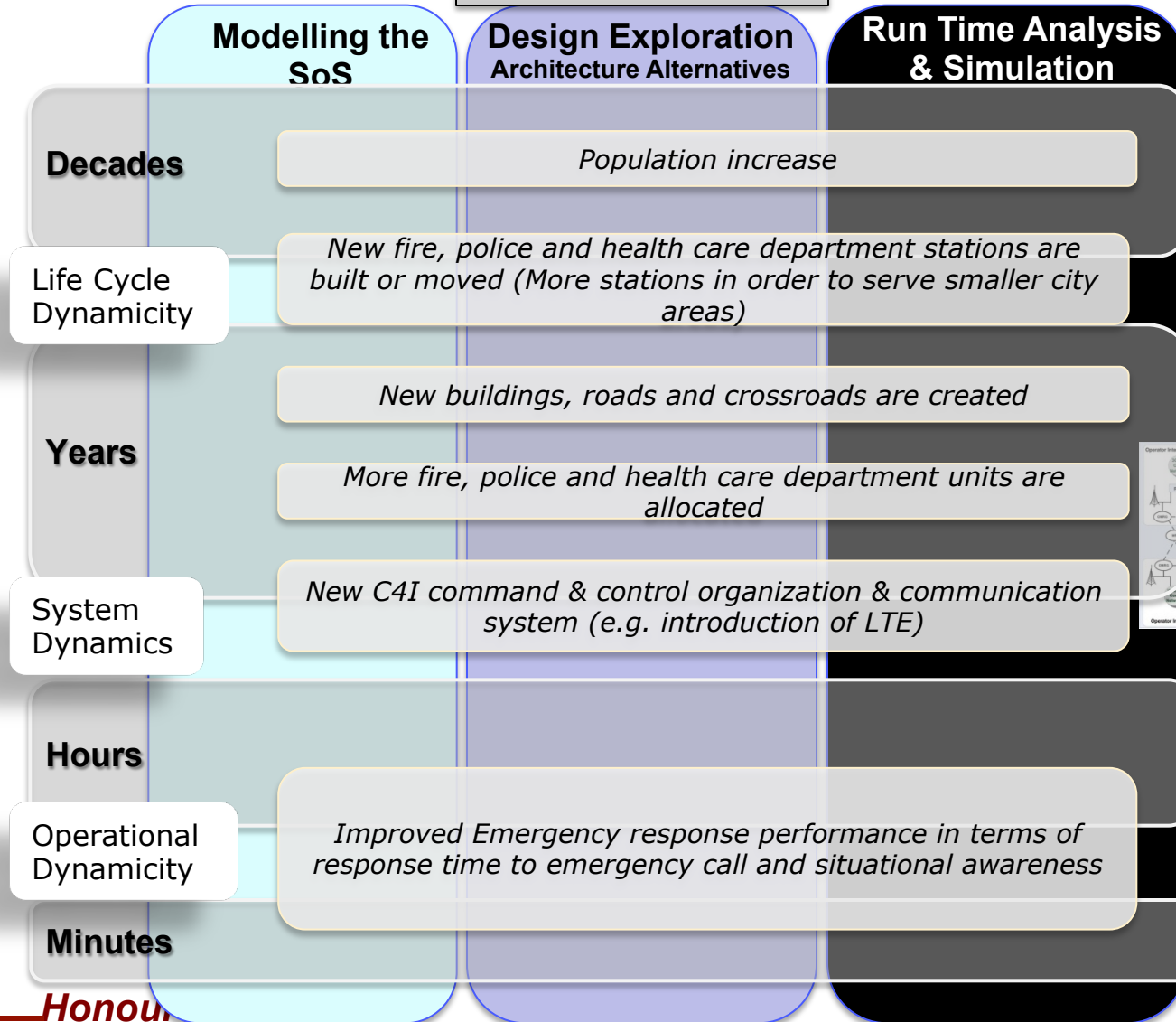


Emergency Response SoS Dynamicity

Primary work: Airbus

SoSE Challenges

SoS operational timeline and dynamicity aspects





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DANSE Methodology

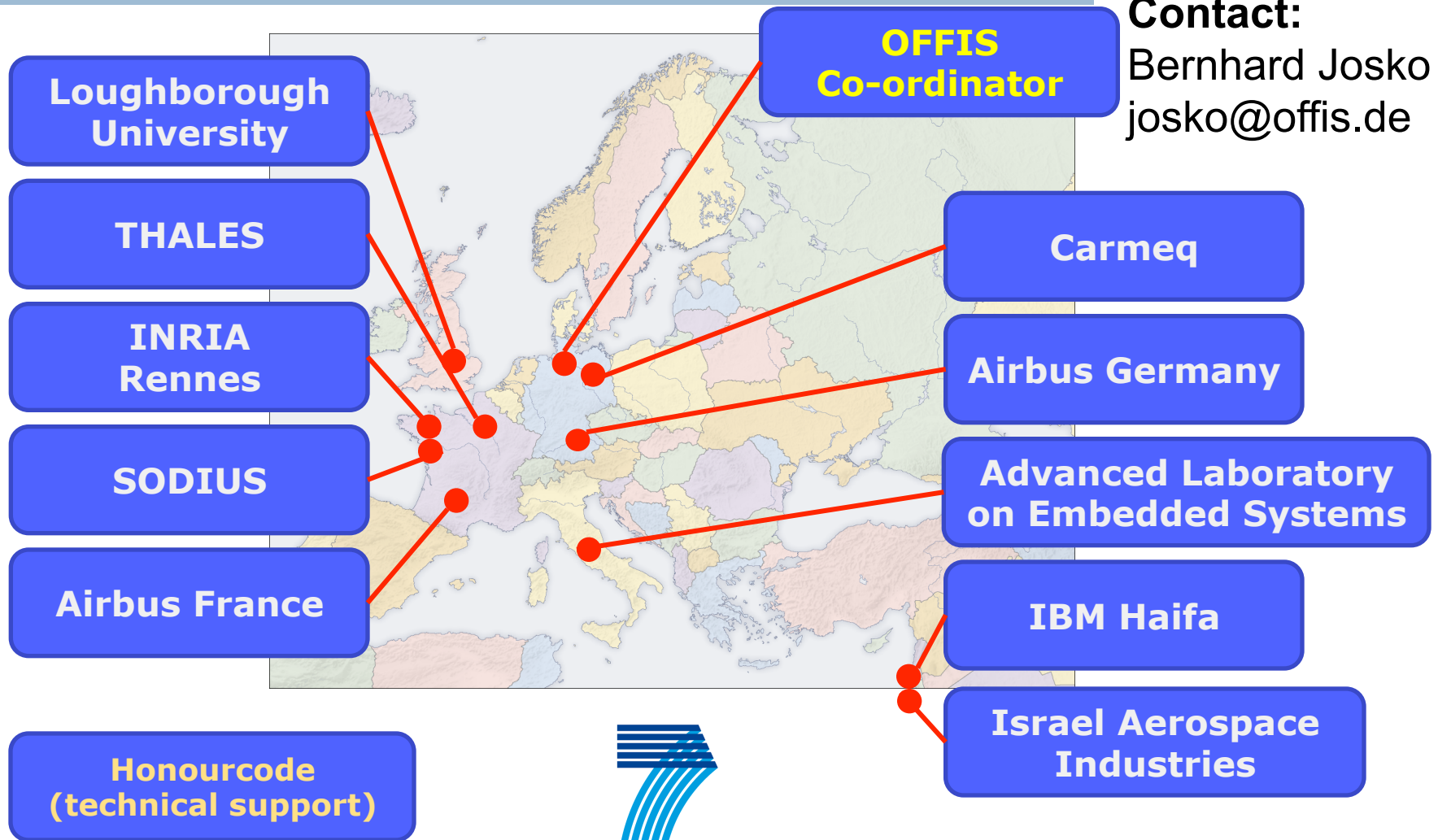
What is the DANSE project?

What is the life cycle of an SoS?

How does the DANSE methodology work in that life cycle?

DANSE Consortium

Contact:
Bernhard Josko
josko@offis.de



DANSE Project

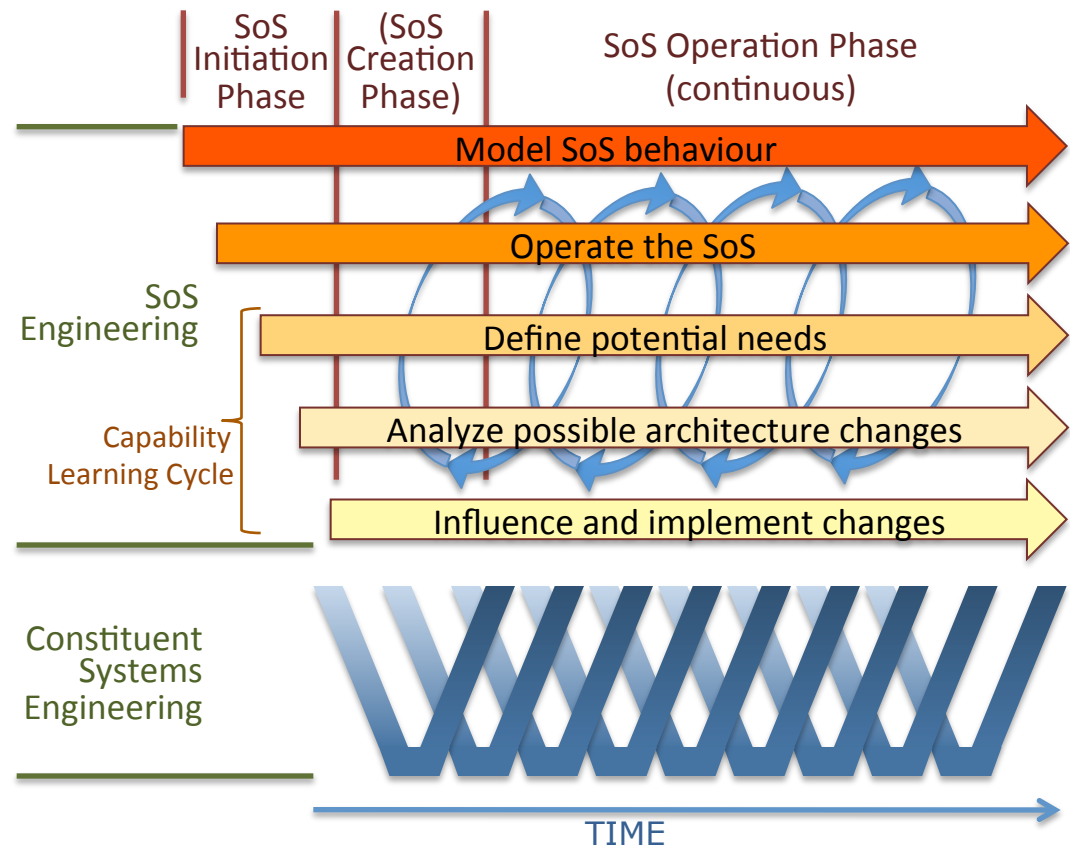


- Develop approaches for SoS engineering (design + manage)
 - Methodology to support evolution, adaptive and iterative SoS lifecycle
 - Contracts as semantically-sound model for SoS interoperations
 - Architecting Approaches for SoS – continuous and non-disruptive constituent system integration
 - Supportive tools for SoS analysis, simulation, optimization
- Validation by real-life test cases
 - Emergency Response; Integrated Water Treatment and Supply; Air Traffic Management; Autonomous Ground Transport

DANSE SoS Life Cycle

Single model to embody the integrating thoughts

- An initiation phase
- Optional creation phase
- Forward movement through the SoS life
- Constant cycling of events/scenarios
- A “capability learning cycle”
 - Where the DANSE benefit happens!
- Normal Vee-based SE in the constituent systems

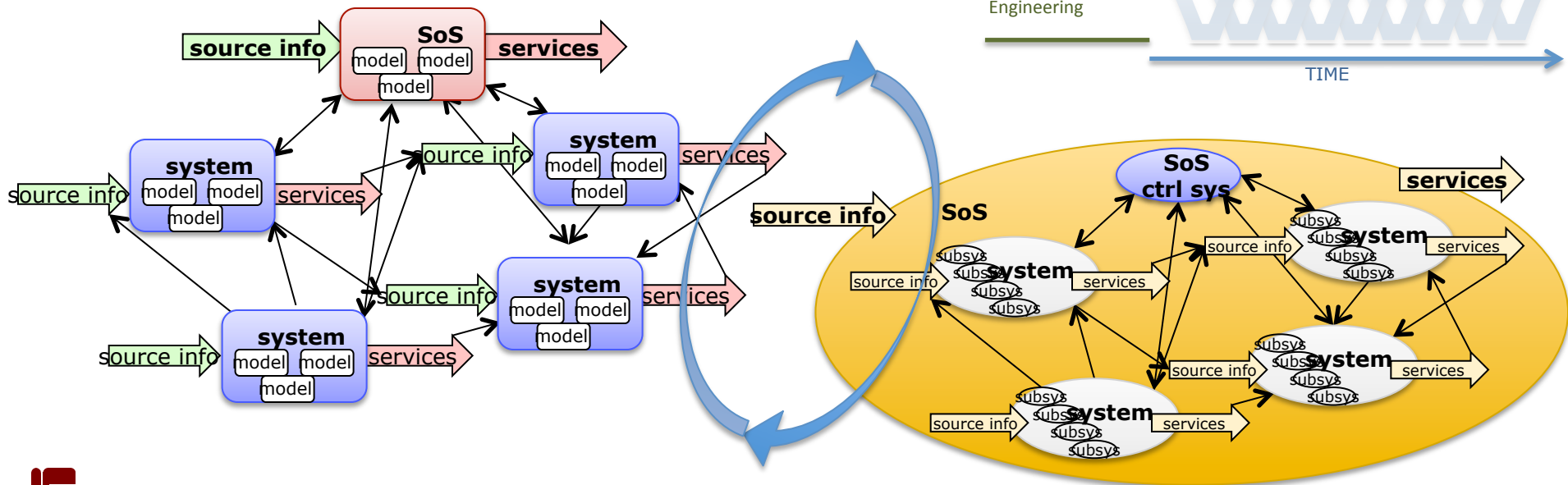
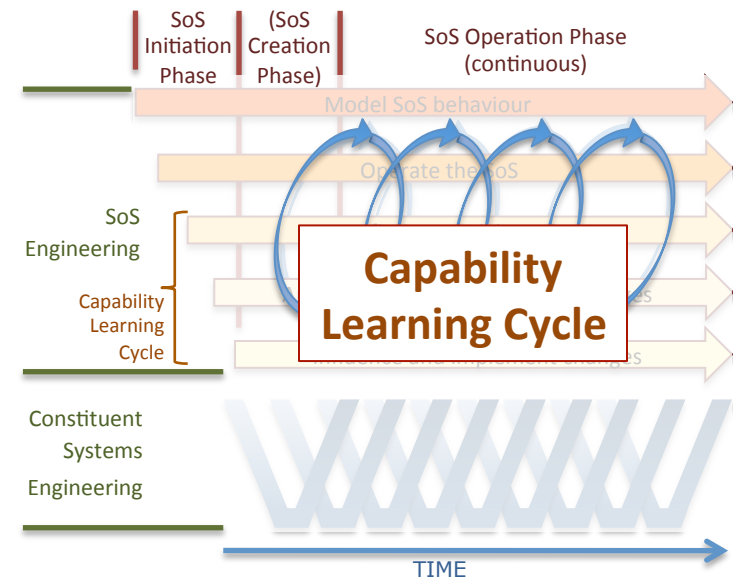


Alternate starting points:

- SoS is acknowledged among existing systems
- SoS is created by a Lead System Integrator

Capability Learning Cycle

- Constantly improve the SoS by a cycle of learning:
 - Define potential needs
 - Analyze possible architecture changes using models
 - Influence and implement changes





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DANSE Solution Methods

What actions can an SoS manager/architect perform
within the DANSE methodology?

Solution Methods

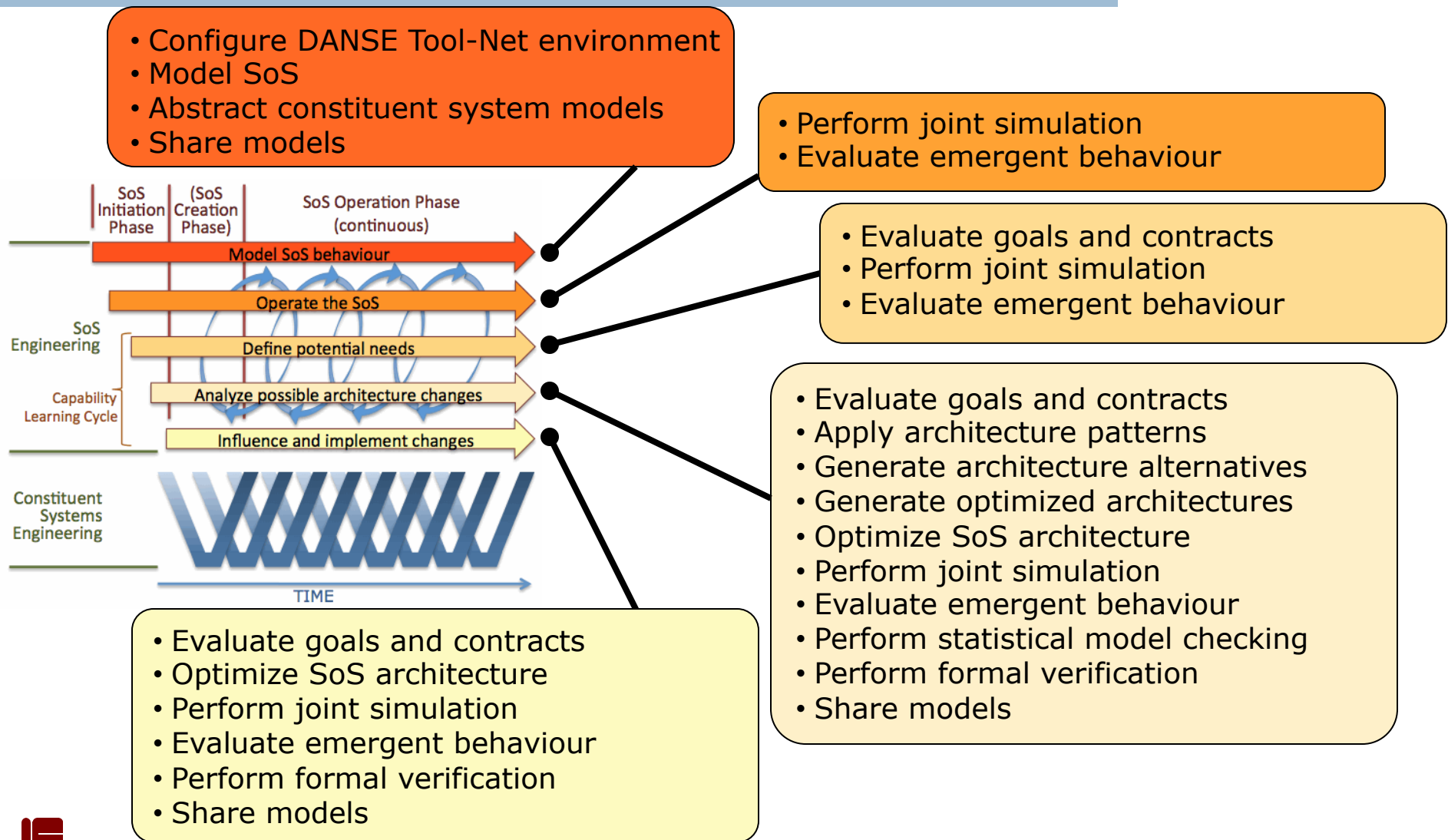
Nbr	Solution Method	What it Does
1	Model SoS	Create UPDM SoS model, particularly focused on the SoS behaviour
2	Abstract CS model	Make a pre-existing (or new) constituent system model available for joint use with the SoS model
3	Apply architecture patterns	Build or enhance the SoS model by the use of a repository of useful patterns, proven by prior use
4	Generate architecture alternatives	Create multiple architecture alternatives for analysis, by the use of graph grammar constructs
5	Generate optimized architectures	Create and evaluate multiple architecture alternatives using concise modelling, with selection of an optimum

Solution Methods

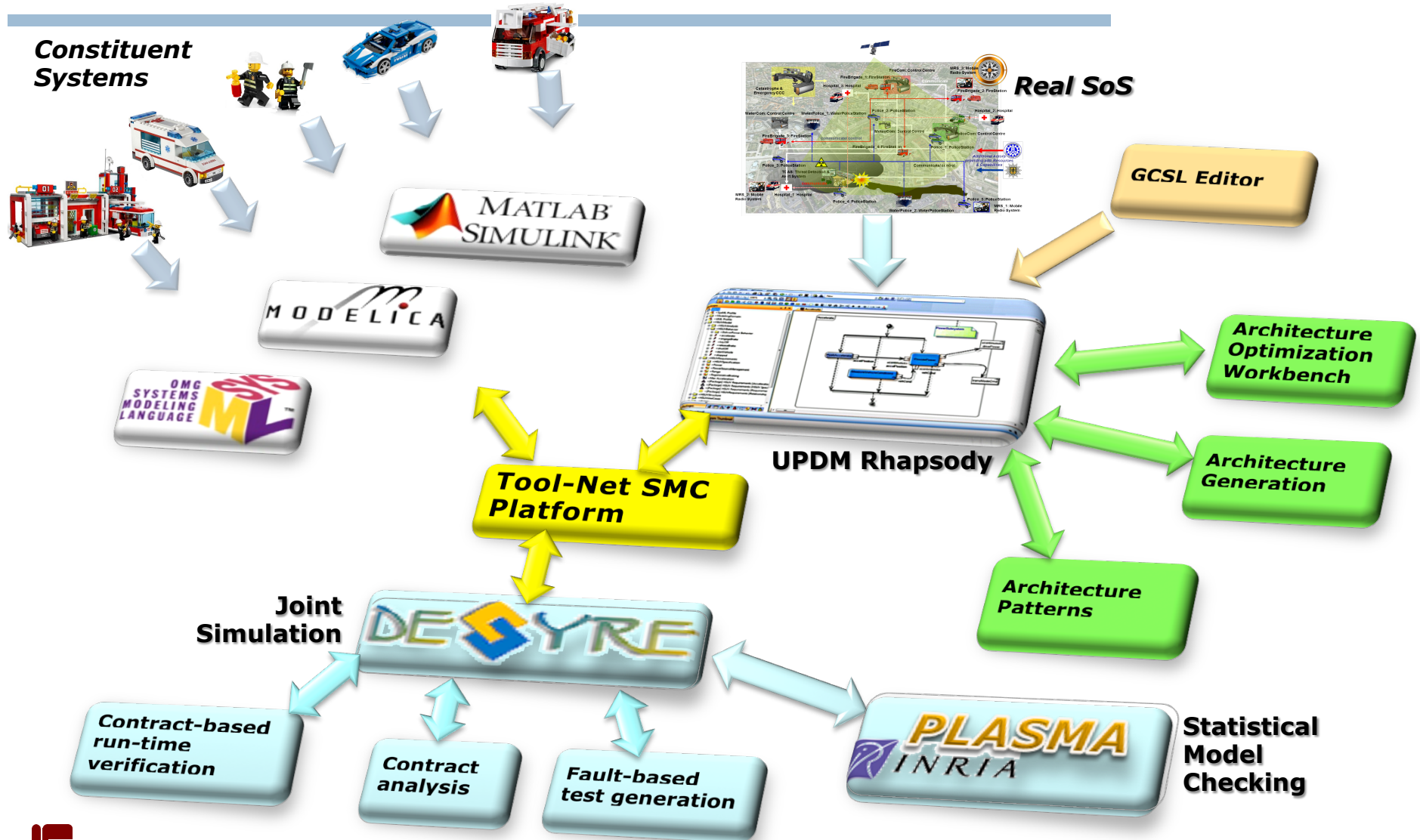
Nbr	Solution Method	What it Does
6	Perform joint simulation	Time-based execution of a joint simulation using SoS and CS models
7	Perform statistical model checking	Identification of simulated performance levels against parameters/goals
8	Evaluate emergent behaviour	Confirmation/discovery of desired or unknown SoS emergent behaviours
9	Evaluate goals and contracts	Definition of SoS/CS goals/contracts, with automated checking during simulation
10	Perform formal verification	Knowledge of time-based compliance against formal requirements
11	Configure DANSE Tool-Net environment	Installation of necessary tools, ontologies, rules, and clients to perform DANSE modelling
12	Share models	Share SoS or CS models with other Tool-Net participants

Solution Methods in the Lifecycle

Primary work: Honourcode



DANSE Tools





DANSE

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DANSE Tools

What automated tools does DANSE provide to support the solution methods?

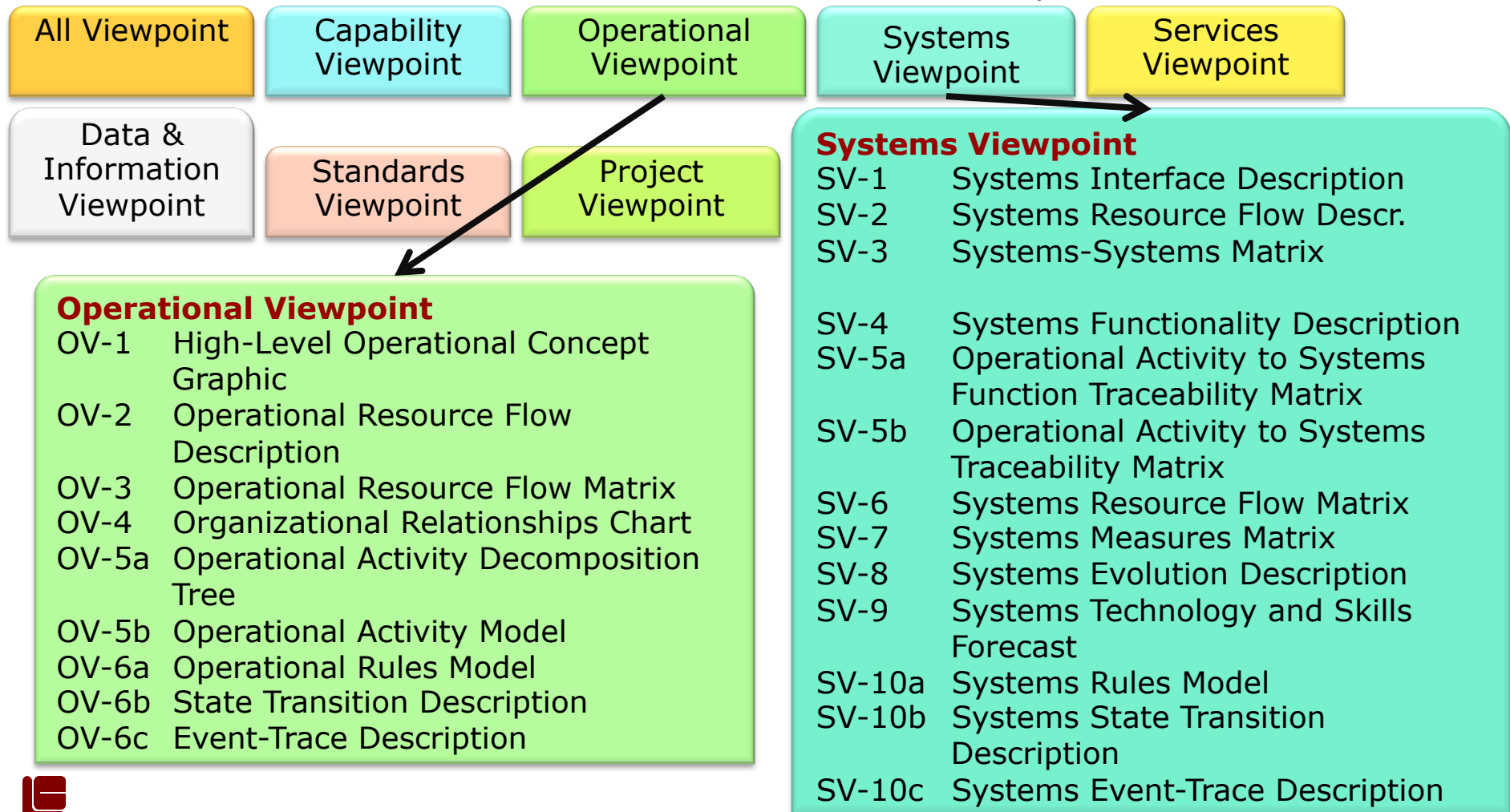
Solution Methods Modeling



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UPDM Overview

- “Unified Profile for DoDAF and MoDAF,” also covers NAF



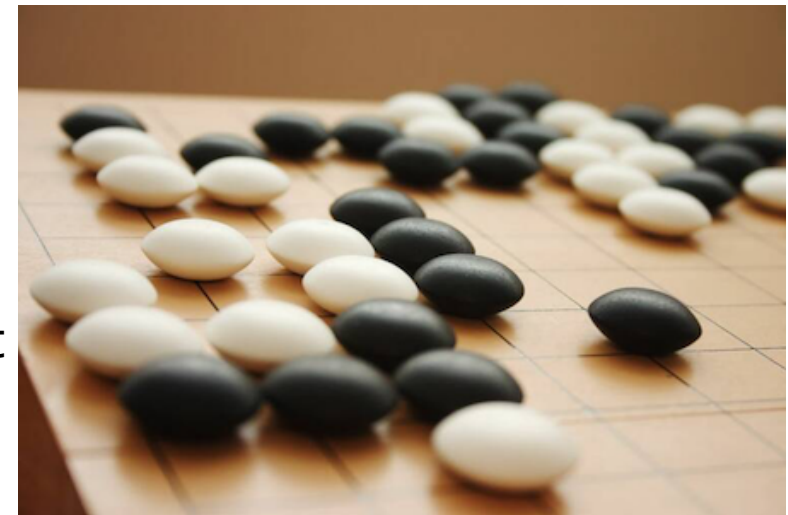
Executable UPDM Views

- SoS model should be executable as a simulation
 - Compare results with real world
 - Project "what if" scenarios
- These views support execution, lead to joint simulation

View	Name	Simulation
OV-5a	Operational Activity Decomposition Tree	SysML BDD, IBD: structure of OV executable elements
OV-5b	Operational Activity Model	SysML Use Case, Activity forms
OV-6b	State Transition Description	SysML State diagrams
OV-6c	Event-Trace Description	SysML Sequence diagrams
SV-1	Systems Interface Description	SysML BDD, IBD: structure of SV executable elements
SV-4	Systems Functionality Description	SysML Use Case, Activity forms
SV-10b	Systems State Transition Description	SysML State diagrams
SV-10c	Systems Event-Trace Description	SysML Sequence diagrams

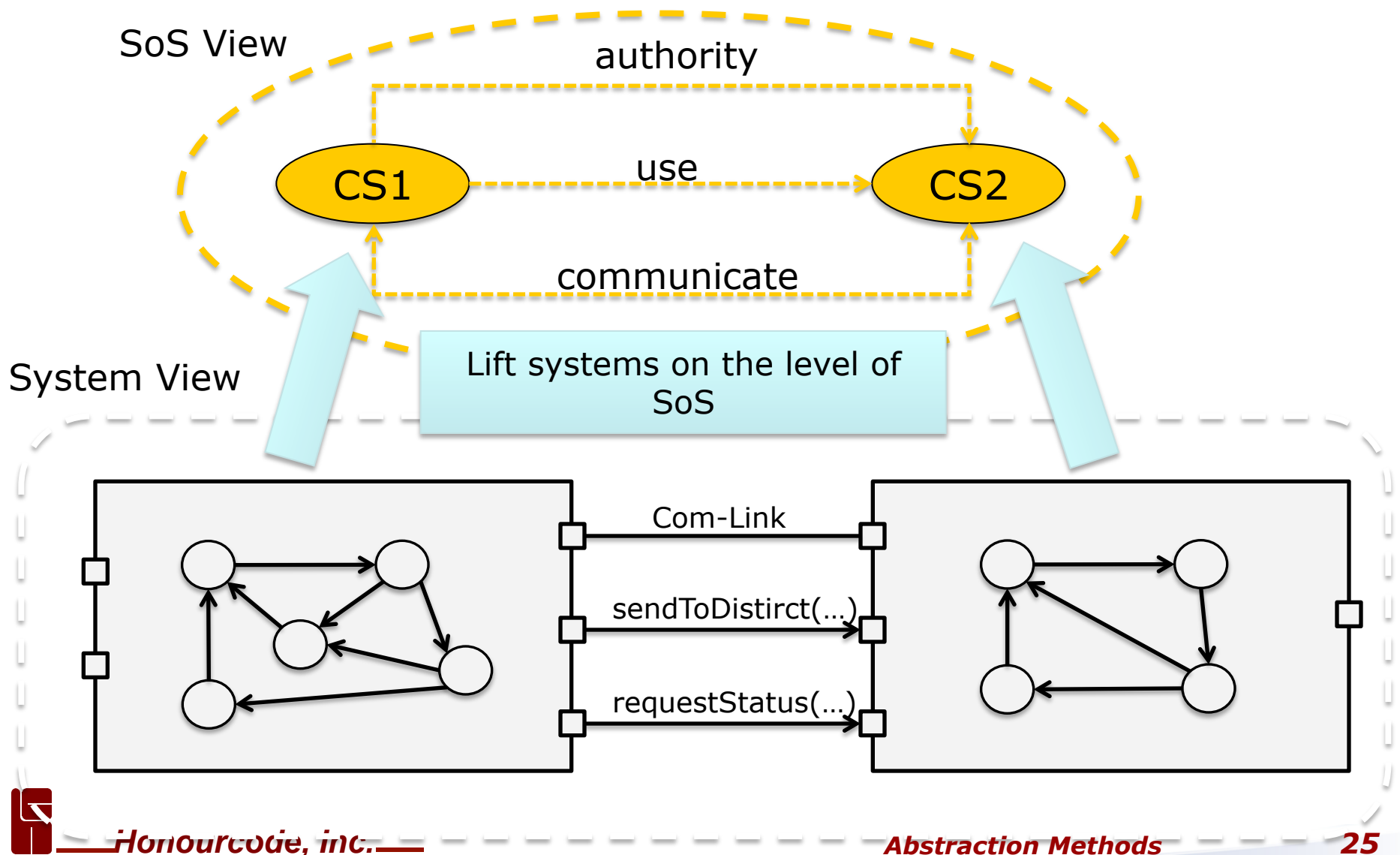
Progressive Level of Detail

- No “Big Bang” – complexity of SoS prevents ability to create a full SoS model
 - Constituent systems changing on their own
 - Do the math ... SoS typically changes monthly!
- Create SoS models at progressive levels of detail
 - High level abstracted representation
 - Quick simulations, moderate accuracy, few emergent behaviours
 - States and modes representation
 - More detail using abstracted CS models
 - Details from CSs as available
 - Best simulation, richest emergent behaviours



Constituent System Models

Primary work: OFFIS



Abstraction Methods

Partner

Group nodes with similar interactions

Flow

Focus on I/O and key parameters

Spotlight

Focus on key elements, others generalized

Steady State

Focus on stable states & transitions among

Statistical

Match statistical behavior w/o details

Timing

Focus on timing issues; other issues ignored

...others also exist

Solution Methods

Goals and Contracts



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Goals and Contracts as SoS “Requirements”



Primary work: OFFIS

- Goal: statement of a desired condition, with quantifiable measurement of the degree to which it is met.
 - *Communications coverage over the urban area (% area covered)*
 - *Response time to a fire (minutes between call and arrival)*
 - *Graded levels of performance*

- Contract: statement of an essential condition, with quantifiable measurement whether it is met.
 - *Within the urban area, response time to a fire is no greater than 15 minutes with probability 99.5%*
 - *Catastrophe and Emergency Center has direct communications with all fire, police, ambulance centers*
 - *Yes/No evaluation*



Goals/Contracts Specification Language (GCSL) Overview



Primary work: OFFIS

- Bridges the gap between
 - Natural language used by people
 - Formal languages required by analysis tools
- Textual pattern with specific semantics
- Formalization process
 1. Define natural language goals/contracts
 2. Structure each statement into the
 - Assumption part ("If X is true...") and the
 - Promise part ("...then Y must be true")
 3. Select a GCSL pattern for the type of relation
 4. Write "X" and "Y" in the GCSL syntax

Catastrophe and Emergency Center has direct comms with all police centers



*If CEC exists...
...then it has direct comms with all police centers*



```
SoS.itsCEC->exists(CEC) implies  
SoS.itsCEC->ForAll(PoliceCenter->  
comms=true)
```

GCSL Editor

- Rhapsody plug-in, part of DANSE UPDM profile extensions
- Create UPDM block
 - Associated with SoS object of interest
 - Contains GCSL statements
- GCSL Editor checks syntax

The screenshot shows the GCSL Editor interface. On the left, a SoS diagram is visible with a red question mark icon. A pink thought bubble contains the text: "0 - Proba(The fire is stoppable in the city in 1 hour) > 99.9%" and "1 - Proba(Mean city area under fire shall be less than 0.01%) > 99%". A blue arrow points from this bubble to a central orange box containing the following text:

0 - Always(true) - Whenever
 $[SoS.itsDistricts.fireArea \rightarrow sum() > 0]$ occurs
 $[SoS.itsDistricts.fireArea \rightarrow sum() = 0]$ occurs
 within $[0, false]$

1 - Always(true) - $MEAN(SoS.itsDistricts.fire \rightarrow sum(), duration/interval) < 0.01/100 * SoS.itsDistricts.area \rightarrow sum()$

A blue arrow points from this text to a GCSL table in the editor window. The table is titled "Constraint: No_0 in SuSGCSL" and has the following content:

GCSL	
Assumption	Always(true)
GCSL_ID	0
Guarantee	$MEAN(SoS.itsDistricts.fire \rightarrow sum(), duration/interval) < 0.01/100 * SoS$

At the bottom of the editor window, there is a "Quick Add" section with fields for "Name:" and "Value:" and an "Add" button. The "Locate" button is also visible.

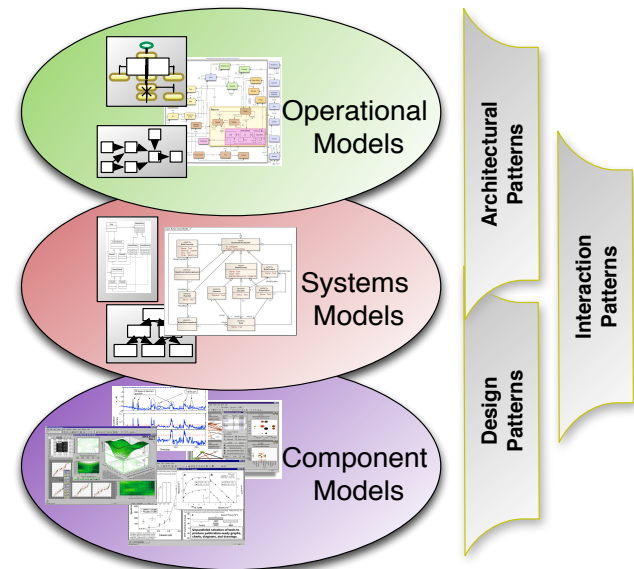
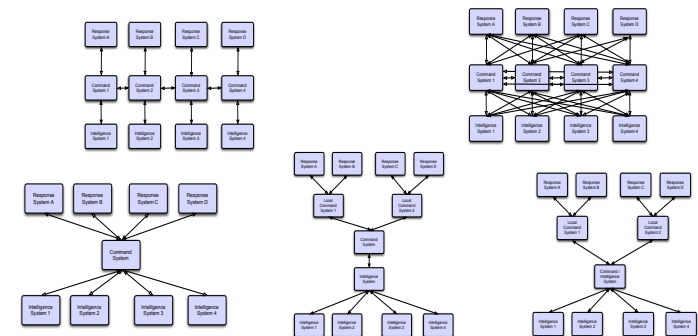
Solution Methods Architecture Exploration



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SoS Architecture Patterns

- Templates to describe solutions to known problems
 - **Context – Problem - Solution**
- Provide a generalized guideline to realize certain architecture characteristics.
- Built on a common anatomy
- DANSE has developed an SoS pattern repository
 - Searchable database of patterns
 - UPDM profiles that can be inserted into the SoS model



Architecture Pattern Anatomy

Primary work: Loughborough Univ

Any key words that may appear in the pattern that will be useful when looking up the pattern in a repository.

The Author of the Pattern

This refers to the problem and why you would use the pattern to address the issue.

Also known as.

Statement of why the pattern would be utilised to address the design problem or situation. It will help understand the structure and consequences later in the pattern.

Name of Pattern

ARCHITECTURE PATTERNS REPOSITORY
Command, Control and Execution Architecture Patterns

[Go to Printing Layout](#)

Catalogue Previous Next All Patterns

Pattern Name

Keywords

Author New Pattern

Pattern Information

Intent
Exercise of authority (invention, advice, opinion, influence, or command) and direction by a control system over assigned resources to achieve accomplishment of the specified mission. The Central Command/Control System governs and exercises full authority over resources.

Also Know
CCC, C3

The pattern allows for a single command centre, which has unquestionable overall authority.

Motivation: Goals

Motivation: Capabilities

- Many points of intelligence access the Centralised Command System, allowing for a more informed decision making process.
- Centralised command facilitates for all knowledge to be in one central location, resulting in more accurate decision making.

Using the Pattern

Structure

Applicability
Root Architecture Patterns

Model (SysML) [Export](#) [Delete](#) [Upload](#)

Model (SysML+Concise) [Upload](#)

Model (UPDM) [Upload](#)

Model (UPDM+Concise) [Upload](#)

Model (Other) [Upload](#)

Diagram of Pattern's Structure

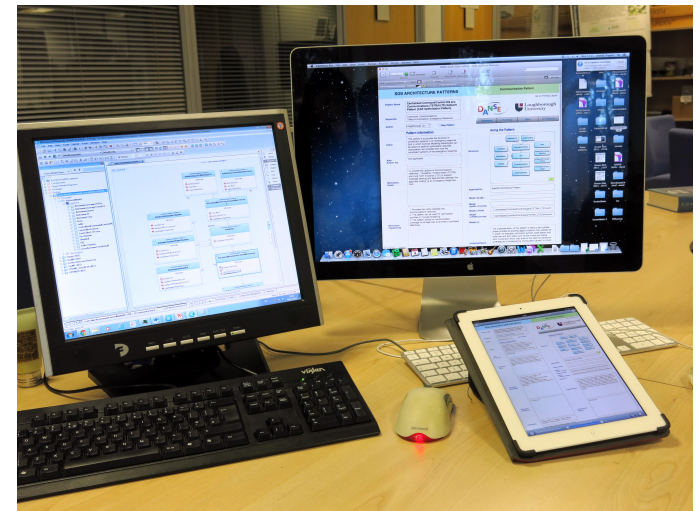
Rhapsody Models Available for Download

14 other fields also available

Architecture Patterns Repository

Primary work: Loughborough Univ

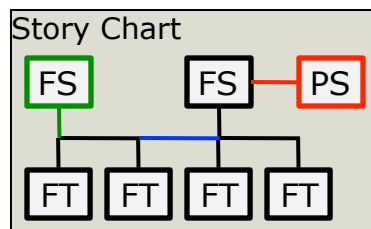
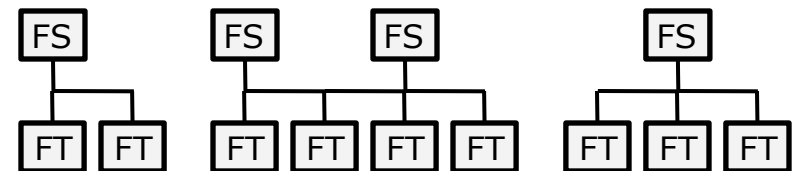
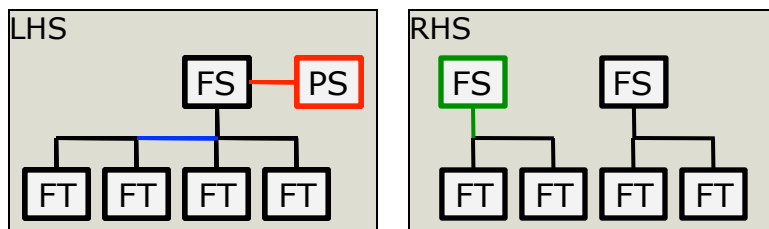
- Architecture Patterns repository includes larger catalog of patterns
 - e.g. UPDM, SysML, Test Cases etc.
- Sophisticated online repository for architecture patterns with powerful search capabilities, option to store new patterns.
- The repository exists itself in three forms;
 - a document-based repository,
 - a repository of IBM Rhapsody profiles, and
 - an online searchable repository with the option to download IBM Rhapsody SysML/UPDM profiles for inclusion in DANSE Tool-net.
- Accessed via:
 - Conventional web browser (all popular browsers supported),
 - Apple iPad running the free FileMaker App – FileMaker Go.
 - User run-time version of FileMaker



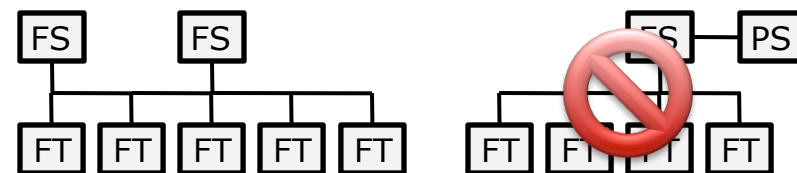
Graph Grammar

- Rules for changing the form of a set of relationships
 - **Left hand side** (LHS) depicts a pattern that can be matched
 - **Right hand side** (RHS) depicts a transformed version
 - **Story Chart** combines LHS and RHS into a transformation rule
- Any successful find of the LHS pattern can be replaced with the RHS
- *This method can automatically generate new architectures*

1. **Reader**: Matched, not changed.
2. **Eraser**: Matched and **removed**.
3. **Creator**: **Added** to the model.
4. **Embargo**: **Prevents the match**.

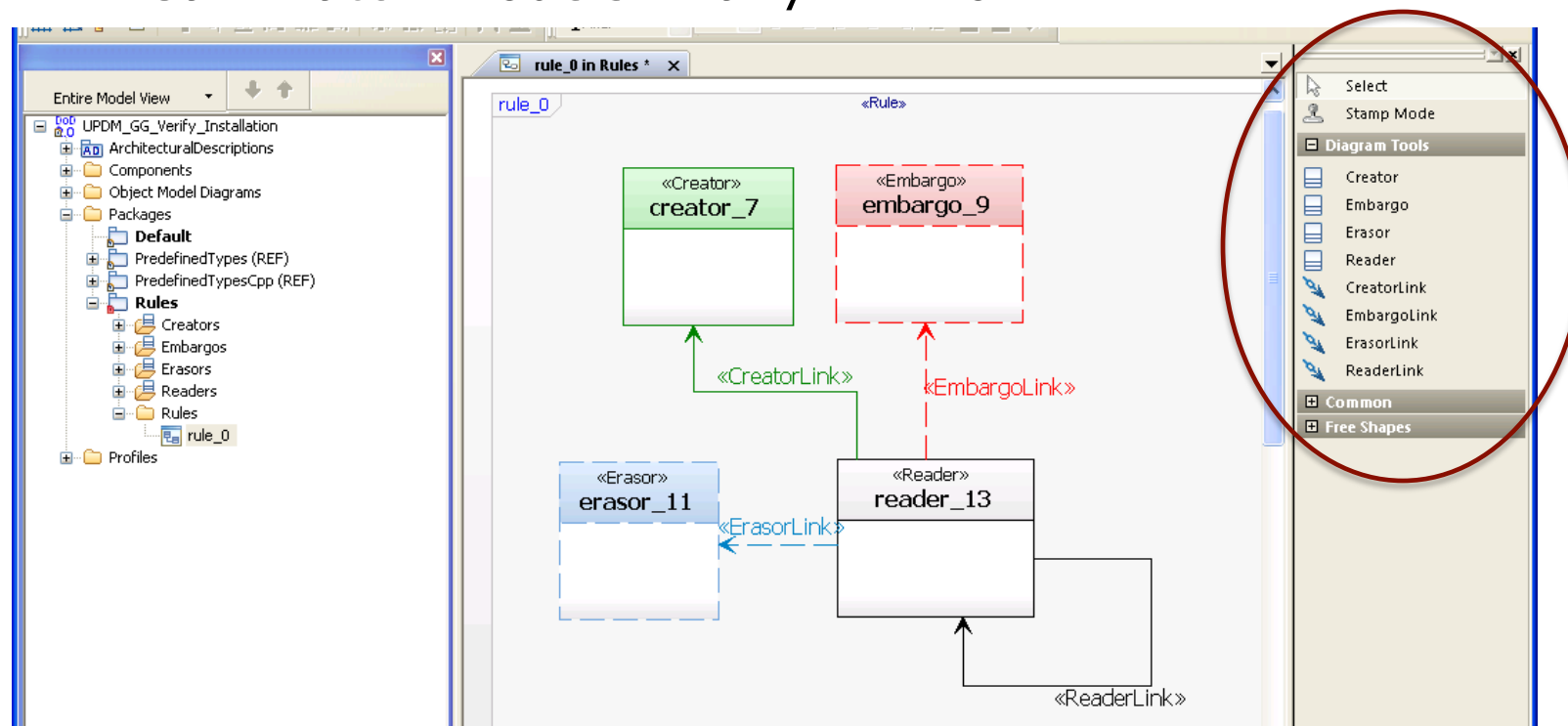


FT: Fire truck
 FS: Fire station
 PS: Police station



DANSE Graph Grammar

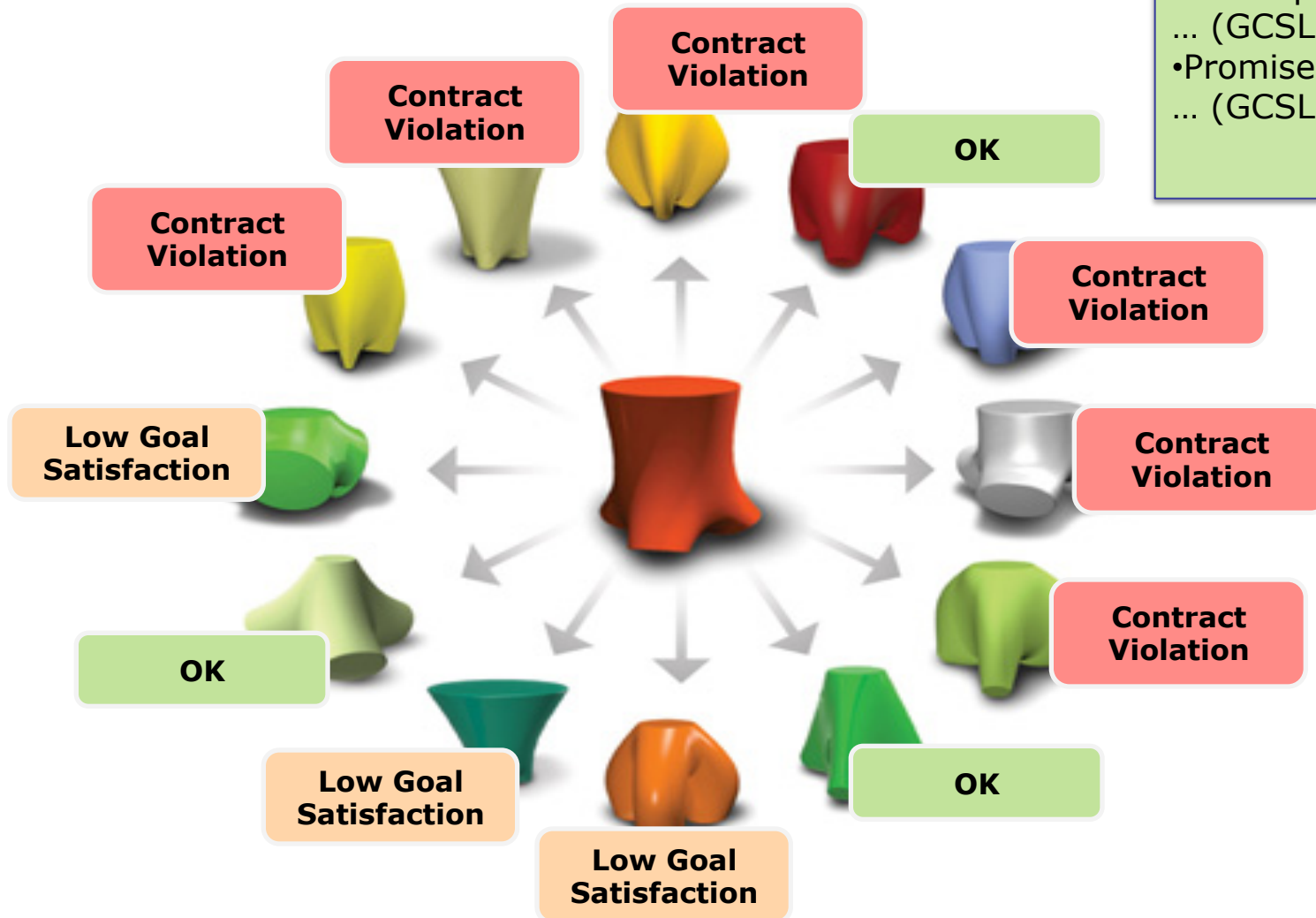
- Story Charts **implemented** as special UPDM diagrams
- Based on a UPDM **profile** to enable the modeling of a rule
- Revised models created automatically by applying the rules
 - Can match models in any BDD or IBD



Exploration of Design Space

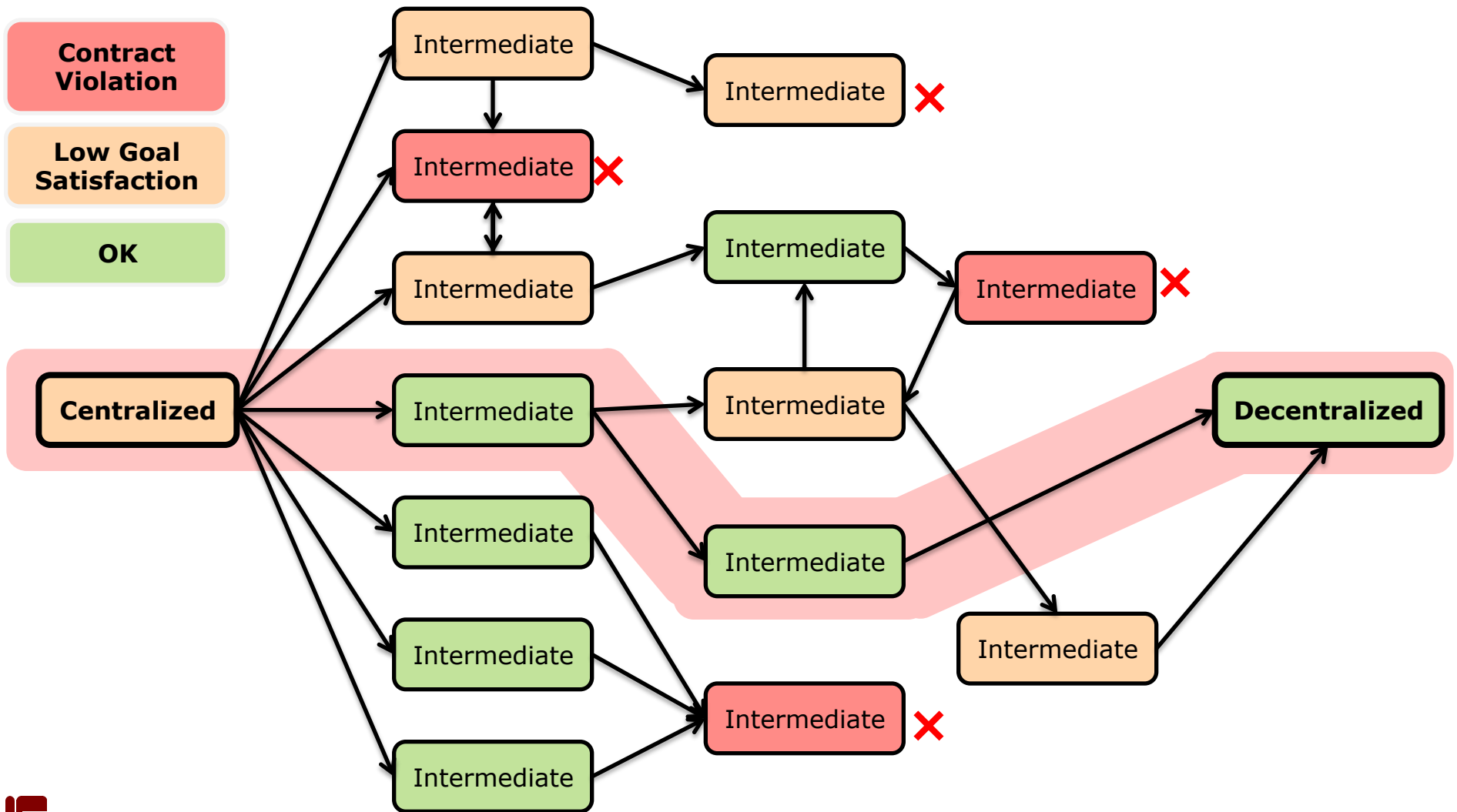
Primary work: OFFIS

SoS contract
 •Assumption ... (GCSL)
 •Promise ... (GCSL)



Reachability of Future Architectures

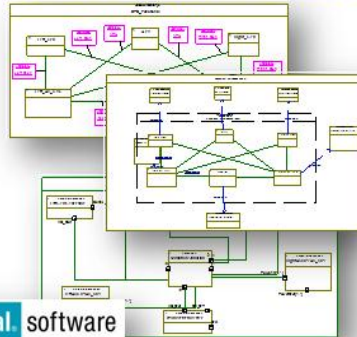
Primary work: OFFIS



Architecture Optimization Concept

Primary work: IBM

1. Describe system through different SysML views, including design alternatives, constraints and goals

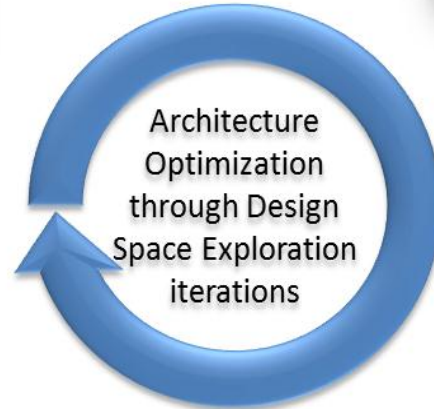


Rational software Rhapsody

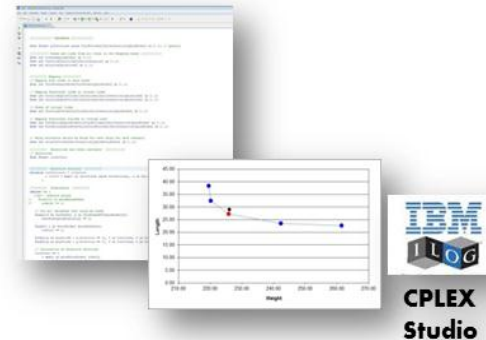
2. Derived Data Schema for Input and output structures

idname	guid	variants
1Junction	GUID e1eb1581-c487-4be2-9fd6-8ce56a53b2ea	Cat.Junction
3Relay	GUID 8feb223d-5bc6-40d6-b179-46b5f3d7e58	Cat.Relay

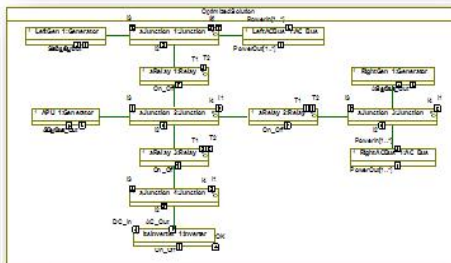
id	name	guid	typed	type name	variants	date from to
23	Processor	GUID 39e126-5e09-4801-4938-e834e34323e2	23	Processor	no_processor	
18	Igniter	GUID 848e973e-72e4-4840-8080-123456789012	10	Generator	no_igniter	
13	Processor	GUID a0c0f7-050e-40e8-07-43-30e736879336c	13	Processor	no_processor	11
18	Igniter	GUID 824e7e050e-07-0e3-0d916168e9e7	13	Bus	no_igniter	
20	Igniter	GUID 14111010-70e4-0212-0e40323333333333	10	Generator	no_igniter	
13	Processor	GUID 1260669-1008-401e-812e-79d31e40042	7	Generator	no_processor	
23	Processor	GUID 2130603-e0d8-077e-0e7e-244831a4714	23	Processor	no_processor	11
23	Processor	GUID 3420700-9814-40e8-910b-037011a124d1	23	Processor	no_processor	11
13	Processor	GUID 8811a19-9b-44d8-07e-1822-46511111	10	Generator	no_igniter	
14	Igniter	GUID 860e47-0068-4740-e032-9721-47e29e9f	13	Bus	no_igniter	
13	Processor	GUID ac7650-7031-4008-8261-d810c1e054e	13	Processor	no_processor	11



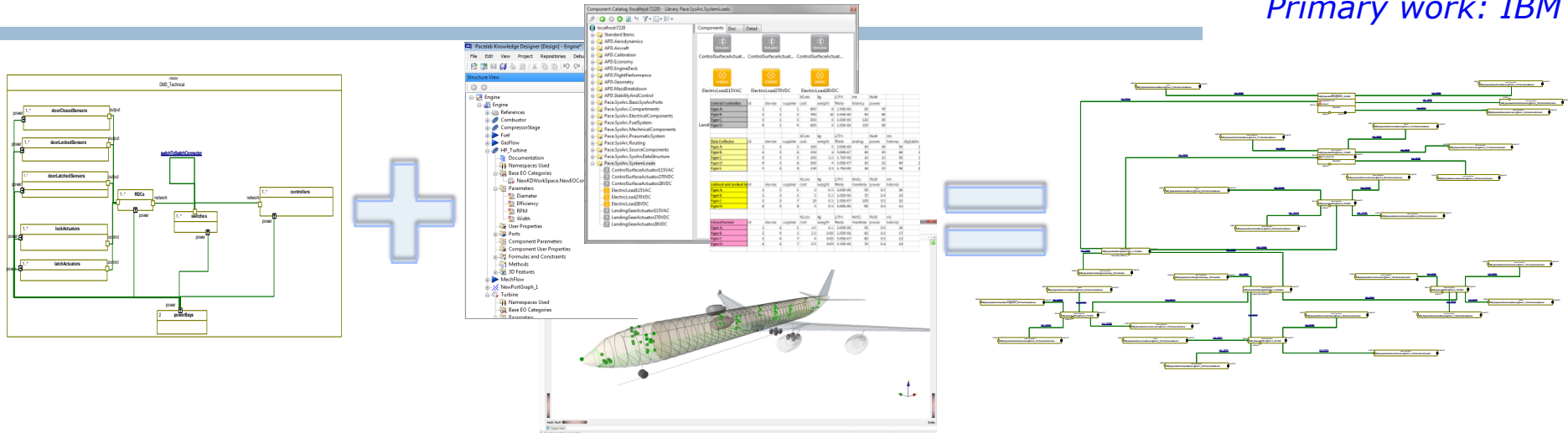
3. Automatic translation (via an interchange format) into Optimization solver



4. Optimized architecture back annotated to SysML model



Concise Modeling



SysML models combined with tabular data

- SysML depicts the system composition rules (architectural template or pattern)
- Tables contain instantiations, variations in quantities or parameters
- Automatic Generation tool creates architecture variants by applying the table data to the template

Dashboard for Architecture Optimization

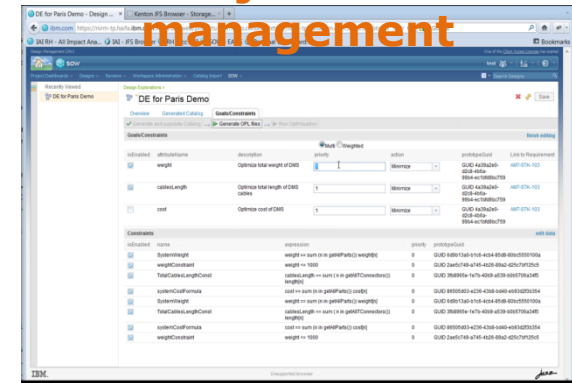
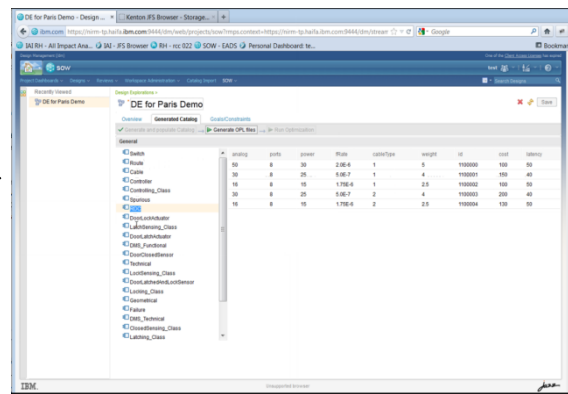
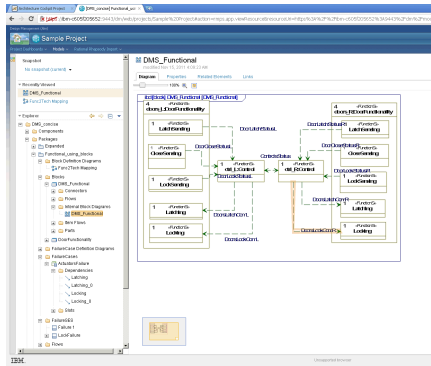


Primary work: IBM

Modeling

Data management

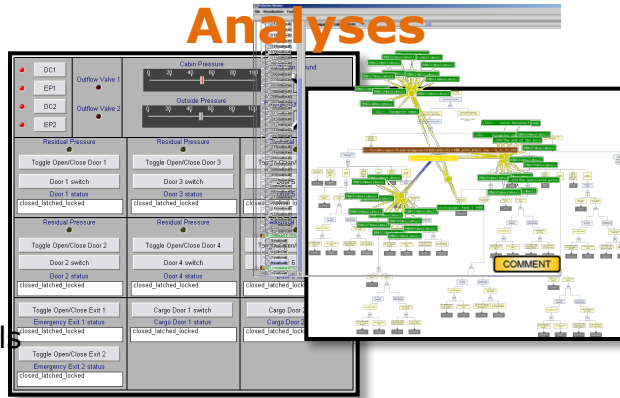
Objectives management



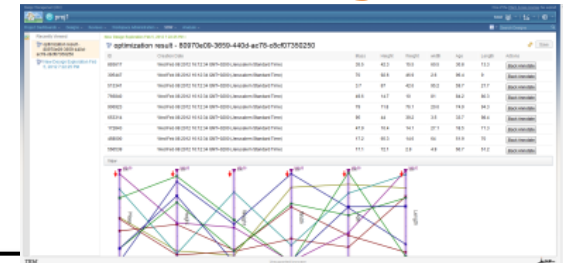
- Single environment
 - Main tool of the Systems Engineer
 - Controlling the design and analysis process
- Based on Design Manager and JTS
- Interaction with modeling environments
 - Review and comment mechanisms
 - Models import / export control
 - Back-end model transformations
- Integration with analysis tools
 - Simulations, computations, domain specific views
 - White-box, black-box
 - Analysis results feedback into models



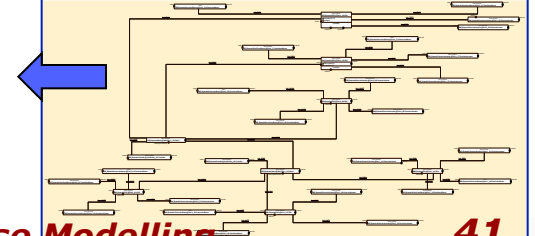
Multiple Analyses



Results management



Back-Annotation



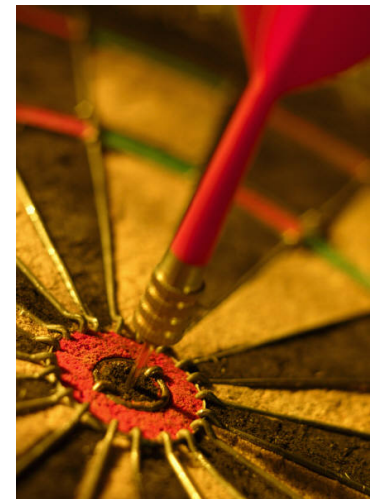
Joint Simulation and Analysis



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12	Share models	Share SoS or CS models with other Tool-Net participants

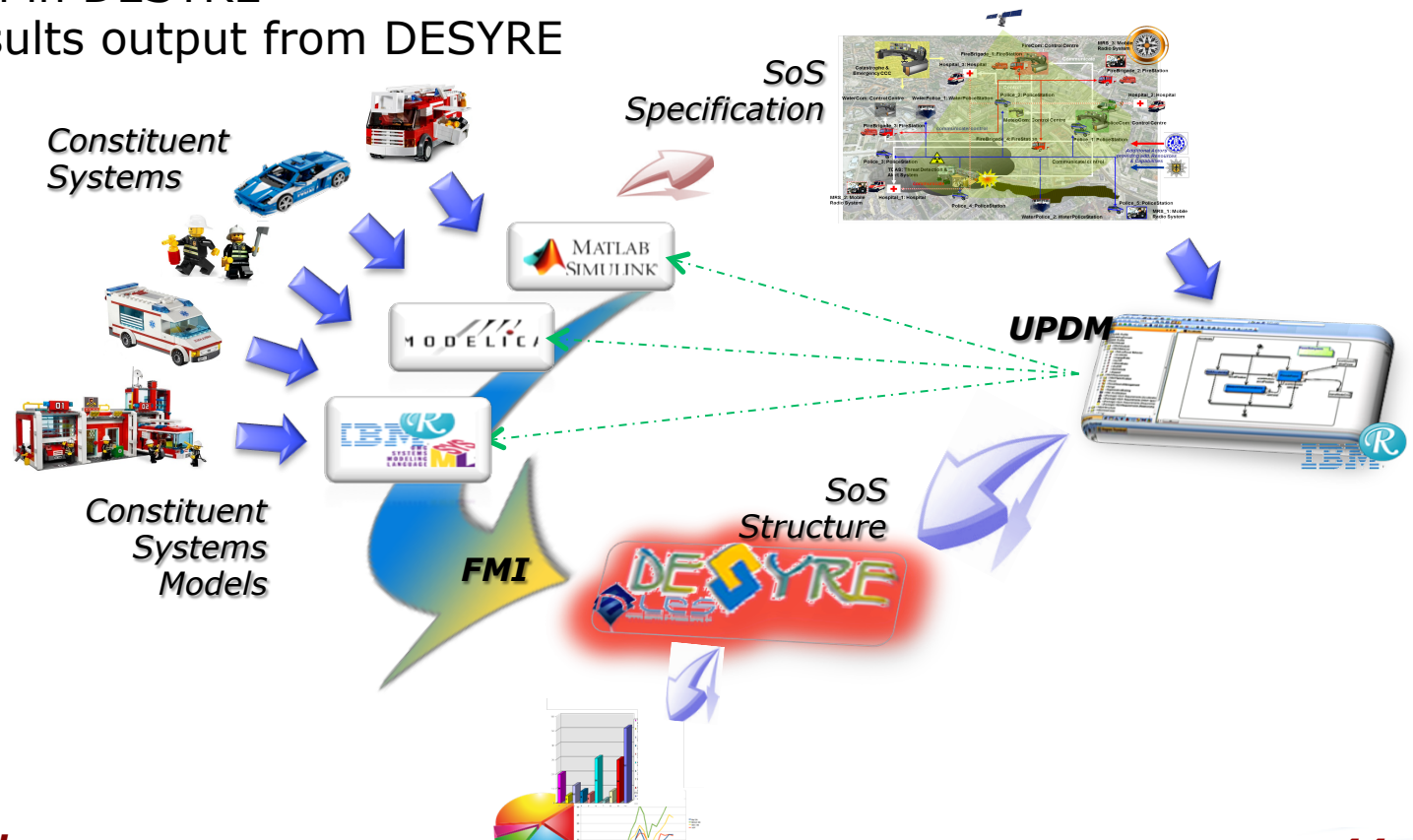
Performance Evaluation Concepts

- Have generated multiple architecture alternatives
 - Patterns application
 - Graph grammar automated generation
 - Concise modeling with optimization
- Need SoS joint simulation to evaluate performance
 - Predict characteristics of interest
 - Evaluate contracts and goals during simulation
 - Dynamic aspects of optimization
 - Stochastic variability
- Provide information for decision analysis



Joint simulation

- FMI standard for component integration
- Constituent system models exported as FMUs from tool
- SoS architecture exported to DESYRE
- FMUs imported in DESYRE
- Simulation run in DESYRE
- Simulation results output from DESYRE



FMI Standard

Tools supporting FMI	Model-Exchange		Co-Simulation		Notes
	Export	Import	Slave	Master	
AVESim	Available	Available	Partial	Partial	Modelica environment from LHM-Imagine
ASIM	Partial	Partial	Partial	Partial	AUTOCAR Builder from Dassault Systemes
Adams	Partial	Partial	Partial	Partial	High end multi-body dynamics simulation software from MSC Software
Atago ACS	Available	Available	Available	Available	Co-simulation environment with AUTOCAR and HIL support
Building Controls Virtual Test Bed	Available	Available	Available	Available	Software environment, based on Ptolemy II, for co-simulation of, and data exchange with, building energy and control systems
CATIA V5R2013	Available	Available	Available	Available	Environment for Product Design and Innovation, including systems engineering tools based on Modelica, by Dassault Systemes
ControlBuilder	Available	Available	Available	Available	Environment for IEC 61131-3 control applications from Dassault Systemes
CoSim4me	Available	Available	Available	Available	Co-simulation Environment from OrcaTec
Quesimexa GENIT	Available	Available	Available	Available	Industrial product for nonlinear (model) Predictive Control (NMPC) from Quesimexa
Quesimexa ModelFit	Available	Available	Available	Available	Software for model verification, state and parameter estimation, using logged process data by Quesimexa
QSPICE	Partial	Partial	Partial	Partial	Fluid power simulation software from FLUIDCON
Qsimica 2013	Available	Available	Available	Available	Modelica environment from Dassault Systemes
EnergyPlus	Available	Available	Available	Available	Whole building energy simulation program
FMI Library from Ilooson	Available	Available	Available	Available	Open source (BDD) C library for integration of FMI technology in custom applications by Ilooson
FMI add-on for NI VeriStand	Available	Available	Available	Available	Manages simulations with FMI for co-simulation V1.0, available from DQPhase
FMI SDK	Available	Available	Available	Available	FMI Software Development Kit from QTIonic
FMI True Centre	Available	Available	Available	Available	Cryptographic protection and signature of models including their early Full storage, secure authentication and authorization for protected co-simulation
IR3 Controller via FMI Toolset for CARMAKER	Partial	Partial	Partial	Partial	via FMI Toolset for CARMAKER from Ilooson (planned for the end of 2012)
JPH	Available	Available	Available	Available	A Java Wrapper for the Functional Mockup Interface, based on FMI SDK
JSSimulation	Available	Available	Available	Available	Open source Modelica environment from Ilooson
MATLAB (via FMI Toolset for MATLAB)	Available	Available	Available	Available	via FMI Toolset for MATLAB from Ilooson
MWORKS 2.5	Available	Available	Available	Available	Modelica environment from Sunhuo Tongquan
MapleSim	Available	Available	Available	Available	Modelica based modeling and simulation tool from Maplesoft
Modelsoft Basic (via FMI Add-in for BDD)	Available	Available	Available	Available	via FMI Add-in for Modelsoft Basic by Ilooson. Offers support for batch simulation of FMI, for BDD
NI LABVIEW	Partial	Partial	Partial	Partial	Graphical programming environment for measurement, test, and control systems from National Instruments
NI VeriStand	Available	Available	Available	Available	Real-Time Testing and Simulation Software from National Instruments
OPTISYS Studio	Available	Available	Available	Available	Modelica environment from Ilooson
Quesimexa	Available	Available	Available	Available	Open source Modelica environment from Quesimexa
Ptolemy II	Available	Available	Available	Available	Software environment for design and analysis of heterogeneous systems
PuMi	Available	Available	Available	Available	For FMI use the open source package PuMi from Ilooson. Also available as part of the JSSimulation platform
SIEMENS	Available	Available	Available	Available	High end multi-body simulation software from SIEMENS AG
Siem 2.4.4	Available	Available	Available	Available	Virtual Integration platform for Software in the Loop from QTIonic
SimulationX 3.4	Available	Available	Available	Available	Modelica environment from ITI
Simulink (via @Source)	Available	Available	Available	Available	via @Source
Simulink (via Dymola)	Available	Available	Available	Available	via Dymola 2013 using Real-Time Workshop
Simulink (via FMI Blockset)	Available	Available	Available	Available	Import of FMI Co-simulation models into Simulink - provided by OrcaTec
Simulink (via FMI Toolset)	Available	Available	Available	Available	via FMI Toolset from Ilooson
TSD	Available	Available	Available	Available	Co-simulation environment from TUC-Thermo
TVET Co-simulation Framework	Available	Available	Available	Available	Communication layer tool to flexibly plug together models for performing a co-simulation, supports for server, monitoring and post-processing included
Verac	Available	Available	Available	Available	Modelica environment from OrcaTec
Virtual Lab Ilooson	Available	Available	Available	Available	Virtual Lab Ilooson is a high end multi-body software from LHM International heterogeneous model integration environment & virtual instrumentation and experimentation laboratory from IPHEN distributed by CST

Over 35 tools support FMI



Modelisar Partners

The FMI specification is developed within the ITEA-2 project Modelisar 2008 - 2011



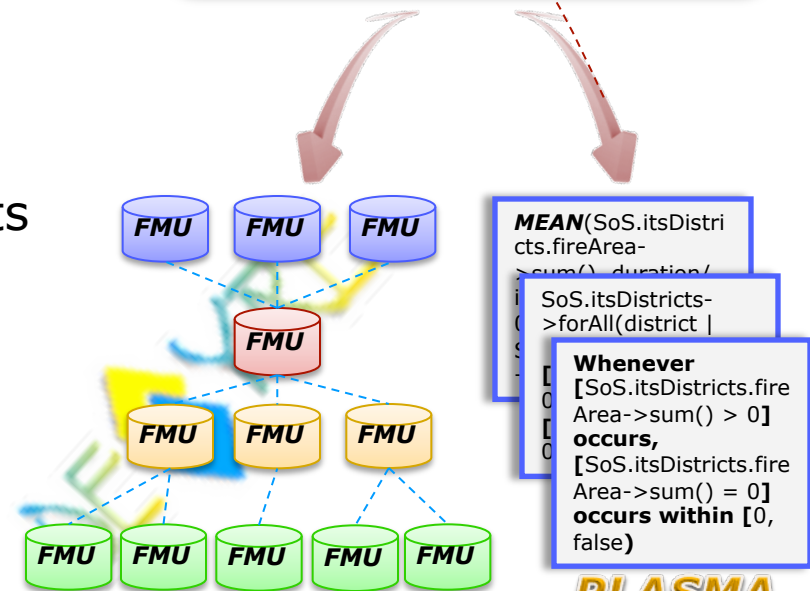
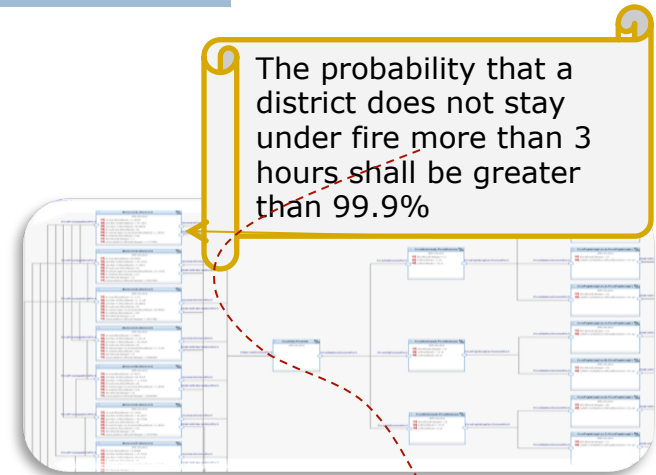
Statistical Model Checking Concepts

- Have multiple architecture alternatives, evaluated
 - Generated through different methods
 - Simulated with statistical results
 - Values for characteristics of interest
- Still must check for formal verification
 - Meet “requirements”?
 - Comply with contracts?
 - Comply with goals?
 - Note: may be many such goals/contracts/requirements; they may conflict



Statistical Model Checking

- Goals and Contracts specified in UPDM model
- GCSL translated into a set of properties that can be evaluated by PLASMA
- UPDM parameters set as observable, traced by the simulator
- DESYRE simulator provides PLASMA with the value assumed by the variables step-by-step during the simulation
- PLASMA verifies the properties
- PLASMA returns the Statistical Model Checking and contract verification results



SoS Emergent Behaviours

- **Emergence** definition
 - Complex pattern formation from more basic constituent parts or behaviors
 - “Properties of the whole that are not evident from the parts.”



Termite cathedral mound

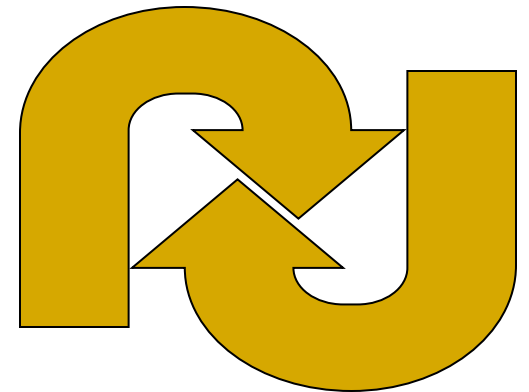
Classes of emergent properties

	Useful	Neutral	Destructive
Designed	Desired capabilities	Facts of design	Accepted trade-offs
Surprise	Exploitable features	Facts of existence	Fearful features

Classical ways to work with Emergent Properties



- Top-down design
 - Identify the desired emergent properties
 - Architect the SoS – component systems and their relationships – to create the desired emergence
 - Identify the acceptable trade-offs
- Bottoms-up integration
 - Simulate and test to find the emergent properties
 - Test for presence of the desired properties
 - Test to discover the surprise properties
 - Evaluate the acceptable trade-offs



Four Methods to Check Emergence

Method	Discovery	Modelling	Analysis
Parameter-based	Observation of parameter variation	Define parameters in the UPDM model	Simulate, observe parameter behaviour, identify anomalies, emergence
Event-based	None	Model GCSL assertions of the desired events	Simulate, determine statistical compliance
Scenario-based	Observe differences in scenario behaviour from expected	Model expected scenarios Create UPDM models of the SoS	Simulate, generate traces, compare traces with the expected scenarios
Test-based	Inspect behaviour over a test objective	Create GCSL test objectives in the UPDM models	Simulate for the test case, check compliance

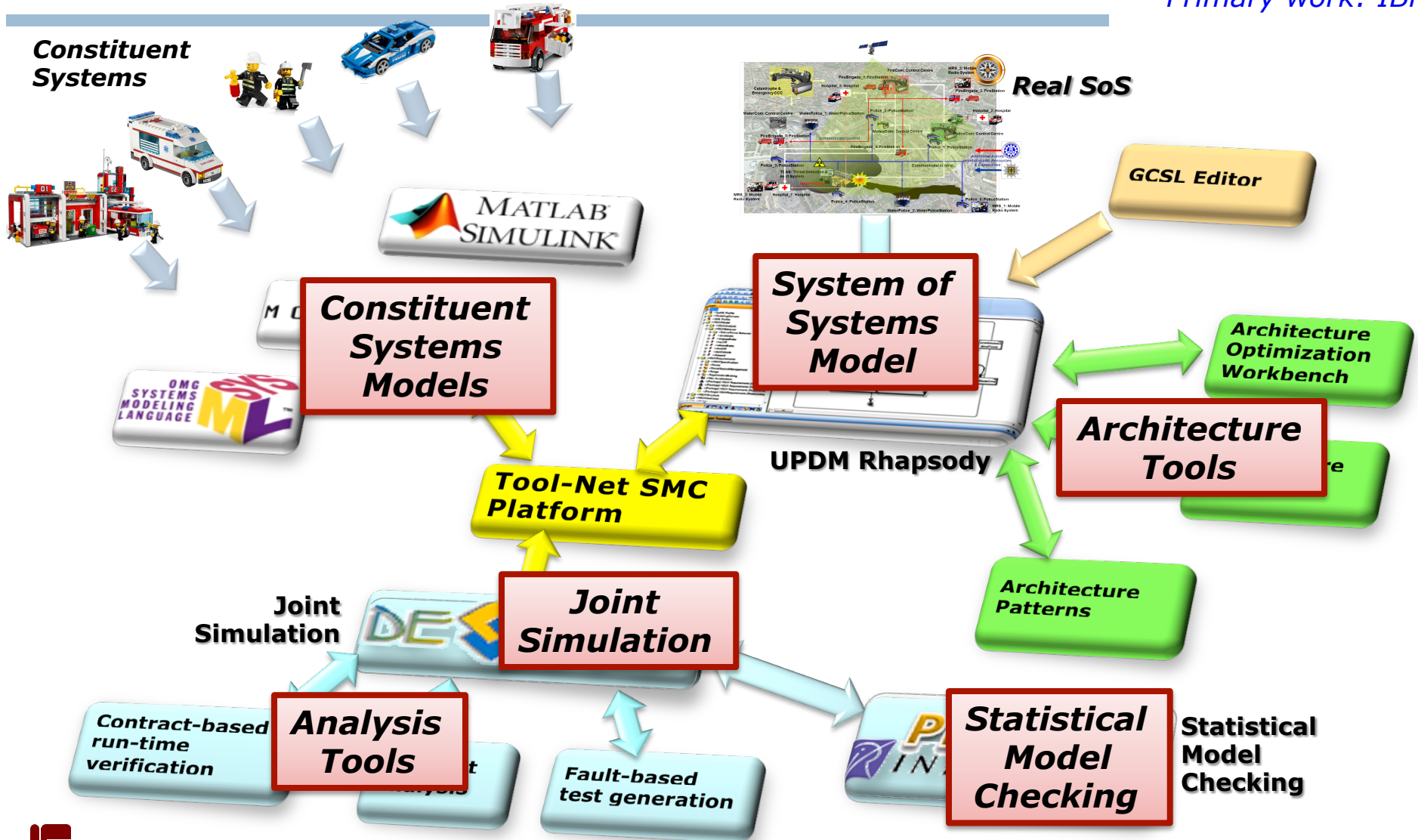
Solution Methods

DANSE Tool-Net



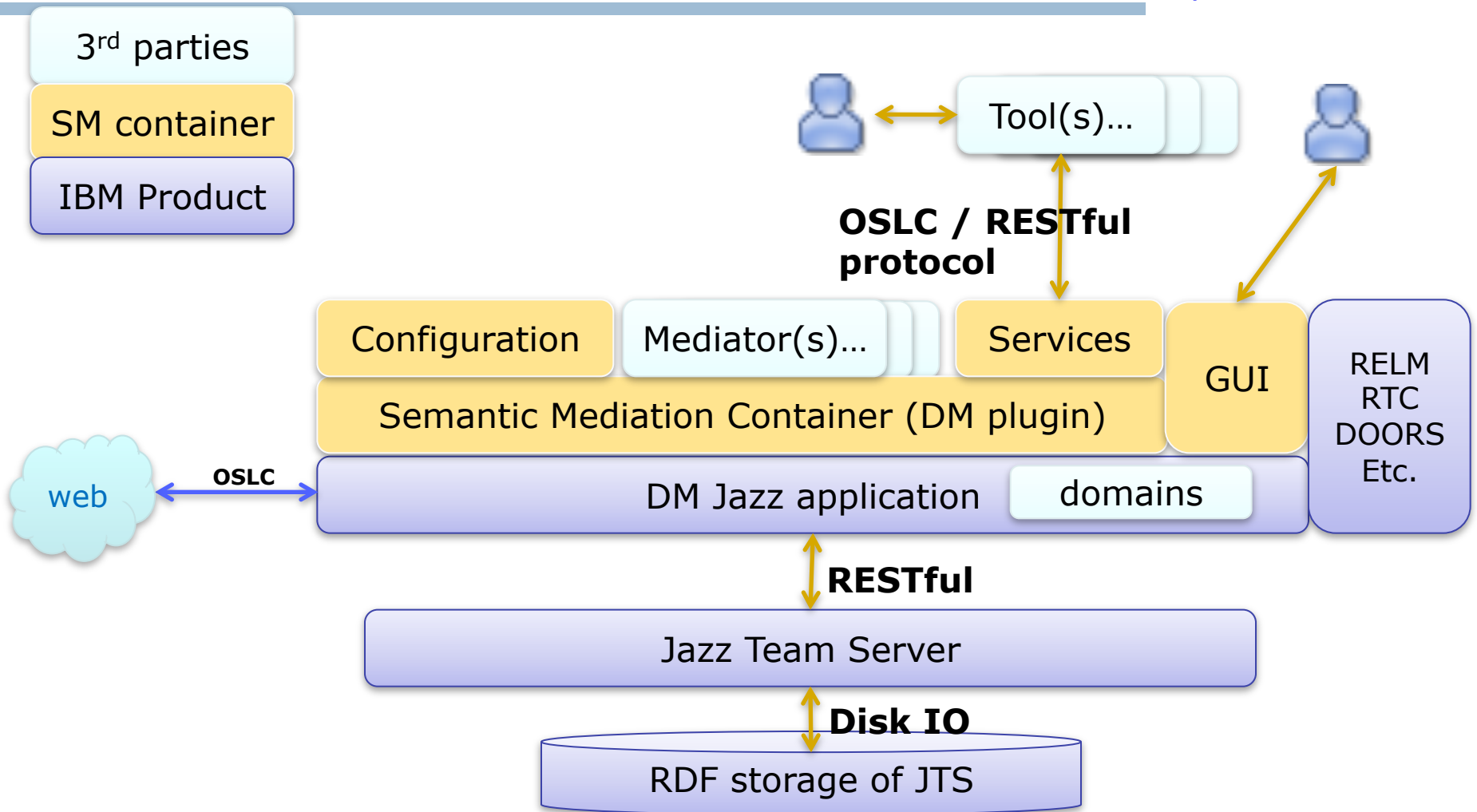
Nbr	Solution Method	What it Does
6	Perform joint simulation	Time-based execution of a joint simulation using SoS and CS models
7	Perform statistical model checking	Identification of simulated performance levels against parameters/goals
8	Evaluate emergent behaviour	Confirmation/discovery of desired or unknown SoS emergent behaviours
9	Evaluate goals and contracts	Definition of SoS/CS goals/contracts, with automated checking during simulation
10	Perform formal verification	Knowledge of time-based compliance against formal requirements
11	Configure DANSE Tool-Net environment	Installation of necessary tools, ontologies, rules, and clients to perform DANSE modelling
12	Share models	Share SoS or CS models with other Tool-Net participants

Tool-Net Connections



Tool-Net Structure

Primary work: IBM/Sodius





DANSE

Designing for **A**daptability and evolution**N** in
System of systems **E**ngineering

Implementation

How does the DANSE methodology support change in
the SoS?

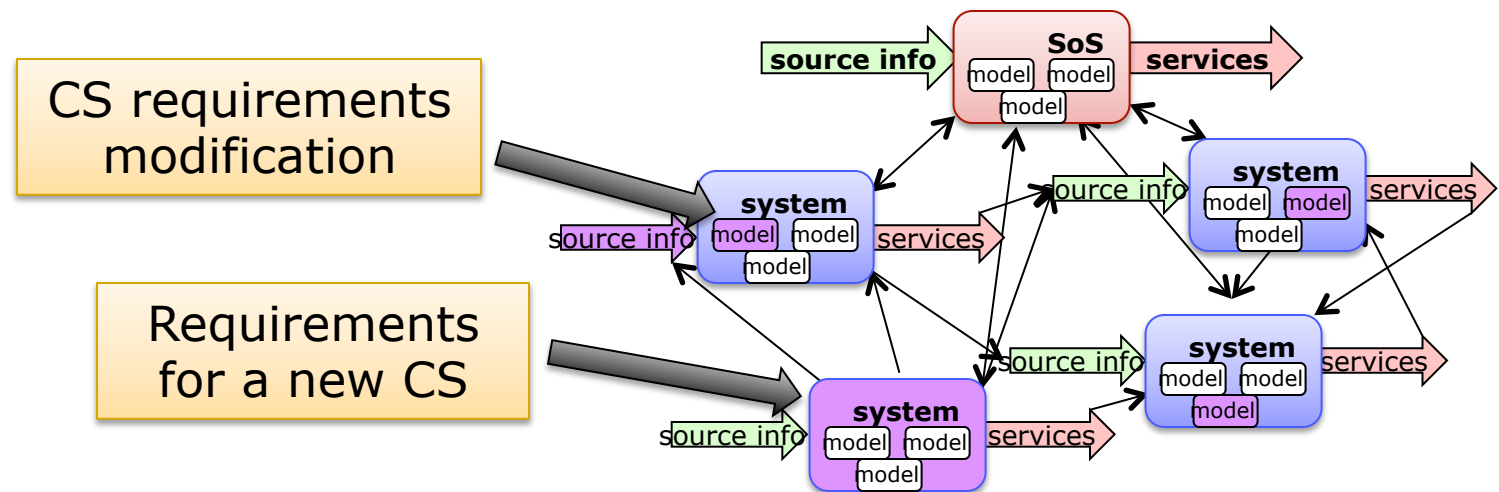
Control vs. Influence

- Traditional systems typically rely heavily on centralized command and control
 - Single acquisition authority
 - Prime contractor
 - Subcontractors via contractual arrangement
 - Suppliers
 - Other stakeholders
- SoSs rely on influence and indirect control
 - Multiple acquisition authorities
 - May be a SoS Integrator
 - Multiple System Contractors
 - Several additional stakeholders

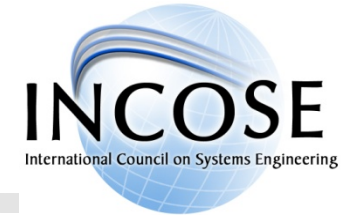


Constituent System Requirements

- Each change to the SoS and constituent system models implies a change to the actual constituent systems



- Changed / new requirements become inputs to acquisition processes
 - Modify existing systems
 - Implement new systems



DANSE

Designing for **A**daptability and evolution**N** in System of systems **E**ngineering

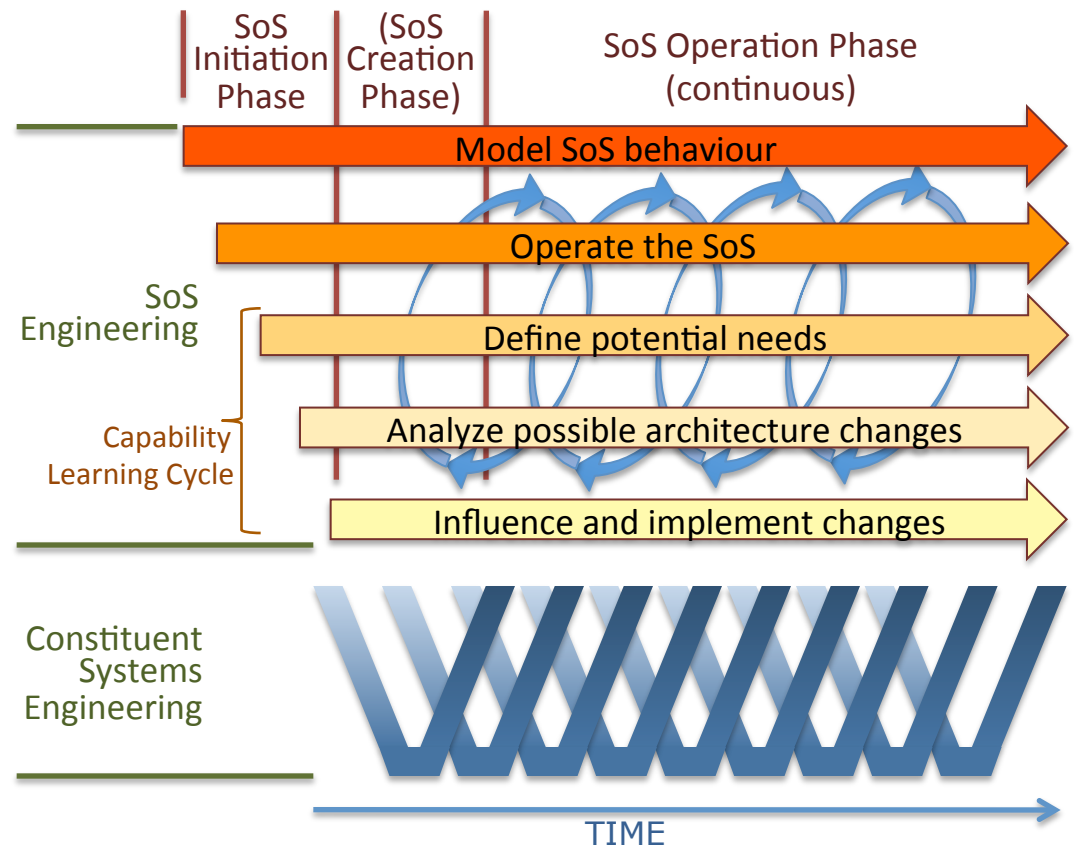
Summary

An effective methodology for SoS evolution supported
by useful tools

DANSE SoS Lifecycle

Single model to embody the integrating thoughts

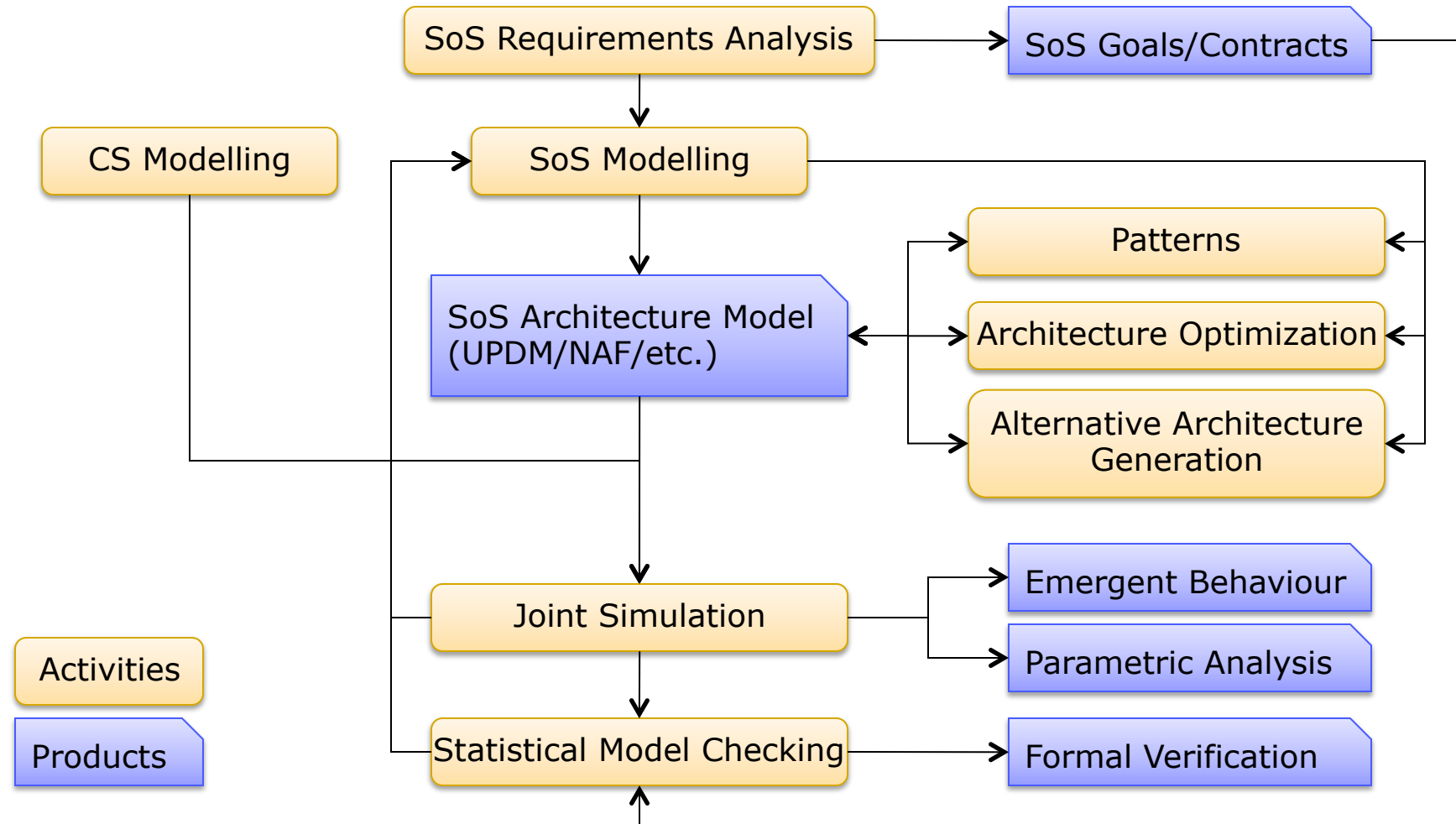
- An initiation phase
- Optional creation phase
- Forward movement through the SoS life
- Constant cycling of events/scenarios
- A “capability learning cycle”
 - Where the DANSE benefit happens!
- Normal Vee-based SE in the constituent systems



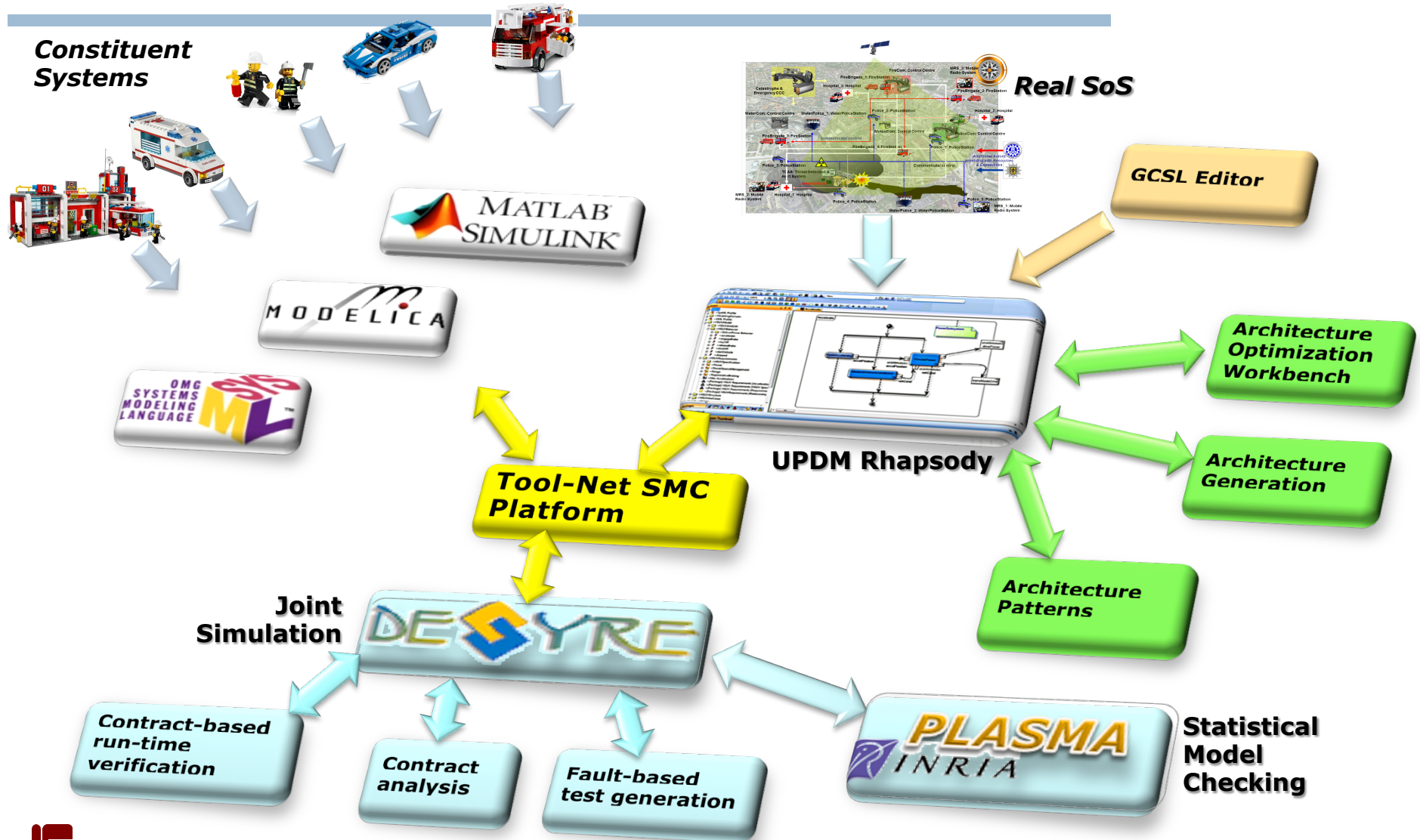
Alternate starting points:

- SoS is acknowledged among existing systems
- SoS is created by a Lead System Integrator

Example "Use Case" of Methodology



DANSE Tools





DANSE

Designing for Adaptability and evolution in System of systems Engineering

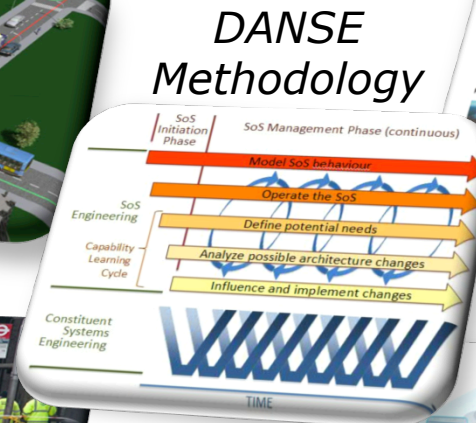
Automated Ground Transport *Carmeq*



Integrated Water Treatment and Supply *IAI*



Emergency Response *Airbus*



Air Traffic Management *Thales*

